

# Shape Analysis via 3-Valued Logic

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Orange handbook

<http://www.cs.tau.ac.il/~msagiv/toplas02.ps>

[www.cs.tau.ac.il/~tvla](http://www.cs.tau.ac.il/~tvla)

# Clarifications

- More precise = Represents fewer states =  $\sqsubseteq$
- Monotone =  $x \sqsubseteq y \rightarrow f(x) \sqsubseteq f(y)$
- Deflationary =  $f(x) \sqsubseteq x$

# Galois Connections

- $\alpha: C \rightarrow A$  and  $\gamma: A \rightarrow C$
- The pair of functions  $(\alpha, \gamma)$  form **Galois connection** if
  - $\alpha$  and  $\gamma$  are monotone
  - $\forall a \in A: \alpha(\gamma(a)) \sqsubseteq a$
  - $\forall c \in C: c \sqsubseteq \gamma(\alpha(c))$
- Alternatively if:  
 $\forall c \in C, \forall a \in A$   
 $\alpha(c) \sqsubseteq a \text{ iff } c \sqsubseteq \gamma(a)$

# Homework

- Define a Galois connection for constant propagation
- Show that every Galois connection abstraction and concretization determine each other
- Read the orange booklet on TVLA
- Download the TVLA system from [www.cs.tau.ac.il/~tvla](http://www.cs.tau.ac.il/~tvla) 2α (5pm)

# Schedule

- ✓ Lecture 1: Abstract Interpretation in the nutshell
- Lecture 2: Operational Semantics & Naive Abstraction of Heap Allocated Data Structures
- Lecture 3: Abstract interpretation of Heap Allocated Data Structures
- Lecture 4: Demo and Applications

# Topics

- A new abstract domain for static analysis
- Abstract dynamically allocated memory

# Motivation

- Dynamically allocated storage and pointers are essential programming tools
  - Object oriented
  - Modularity
  - Data structure
- But
  - Error prone
  - Inefficient
- Static analysis can be very useful here

# A Pathological C Program

```
a = malloc(...);
```

```
b = a;
```

```
free (a);
```

```
c = malloc (...);
```

```
if (b == c) printf("unexpected equality");
```



# Dereference of NULL pointers

```
typedef struct element {  
    int value;  
    struct element *next;  
} Elements  
  
bool search(int value, Elements *c) {  
    Elements *elem;  
    for (elem = c;  
         elem != NULL;  
         elem = elem->next;) {  
        if (elem->val == value)  
            return TRUE;  
    }  
    return FALSE  
}
```

# Dereference of NULL pointers

```
typedef struct element {  
    int value;  
    struct element *next;  
} Elements  
  
bool search(int value, Elements *c) {  
    Elements *elem;  
    for (elem = c;  
         elem != NULL;  
         elem = elem->next;) {  
        if (elem->val == value)  
            return TRUE;  
    }  
    return FALSE  
}
```

potential null  
de-reference

# Memory leakage

```
typedef struct element {
    int value;
    struct element *next;
} Elements

Elements* reverse(Elements *c)
{
    Elements *h,*g;
    h = NULL;
    while (c!= NULL) {
        g = c->next;
        h = c;
        c->next = h;
        c = g;
    }
    return h;
}
```

# Memory leakage

```
typedef struct element {
    int value;
    struct element *next;
} Elements

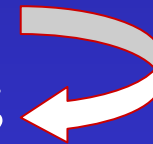
Elements* reverse(Elements *c)
{
    Elements *h,*g;
    h = NULL;
    while (c!= NULL) {
        g = c->next;
        h = c;
        c->next = h;
        c = g;
    }
    return h;
}
```

*leakage of address  
pointed-by h*

# Memory leakage

```
typedef struct element {  
    int value;  
    struct element *next;  
} Elements  
  
Elements* reverse(Elements *c)  
{  
    Elements *h,*g;  
    h = NULL;  
    while (c!= NULL) {  
        g = c->next;  
        h = c;  
        c->next = h;  
        c = g;  
    }  
    return h;  
}
```

✓ No memory leaks



# Example: List Creation

```
typedef struct node {  
    int val;  
    struct node *next;  
} *List;
```

```
List create (...)
```

```
{
```

```
List x, t;
```

```
x = NULL;
```

```
while (...) do {
```

```
    t = malloc();
```

```
    t →next=x;
```

```
    x = t ;}
```

```
return x;
```

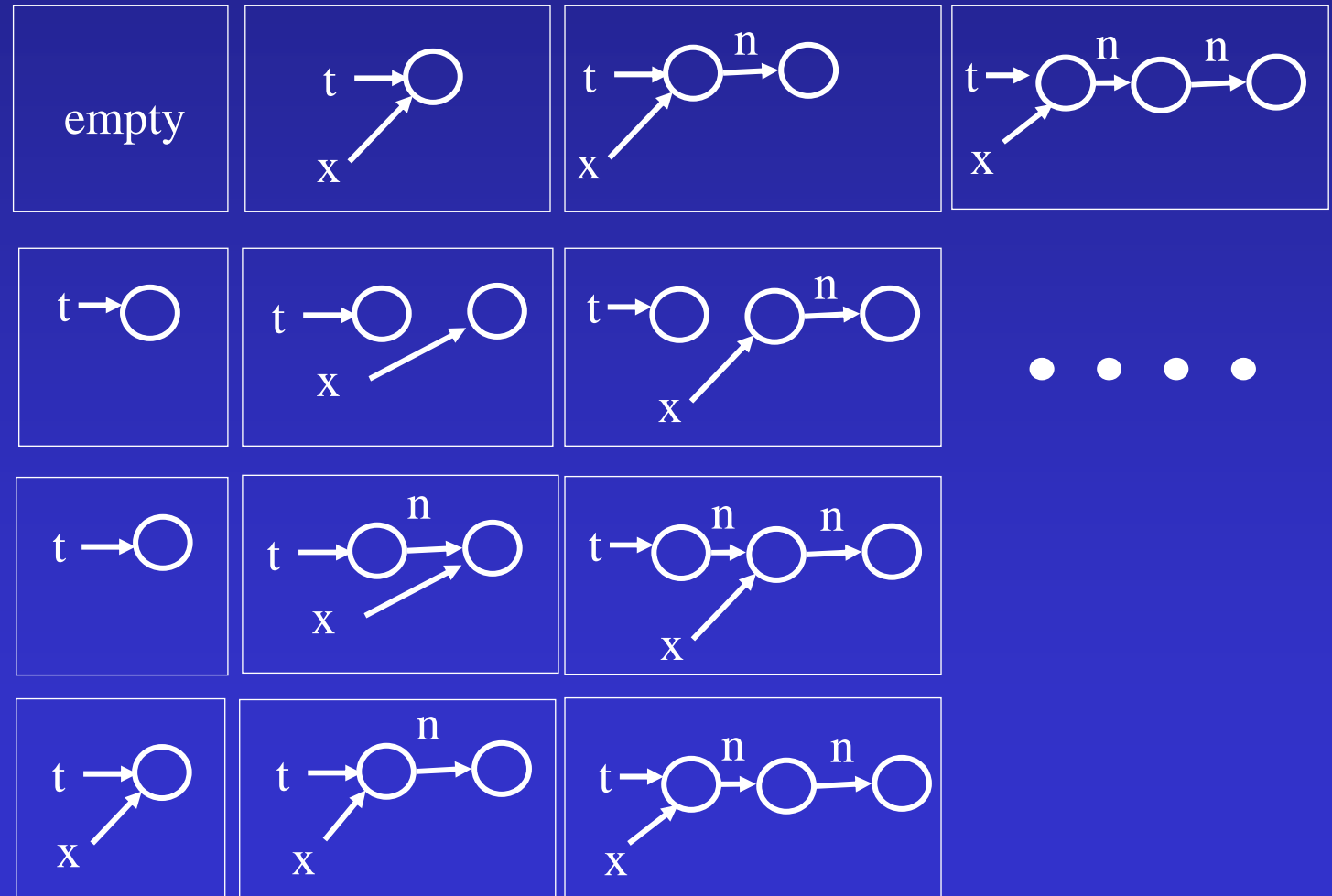
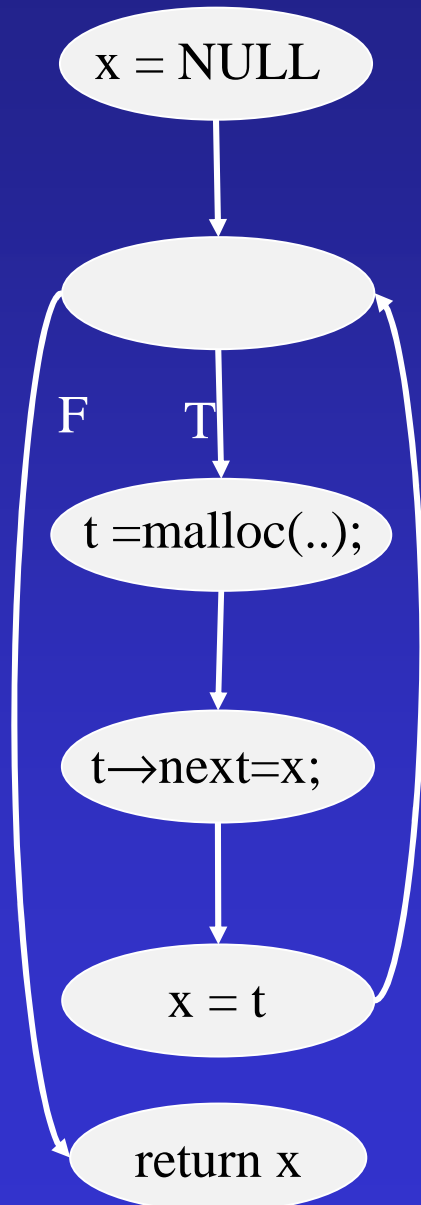
```
}
```

✓ No null dereferences

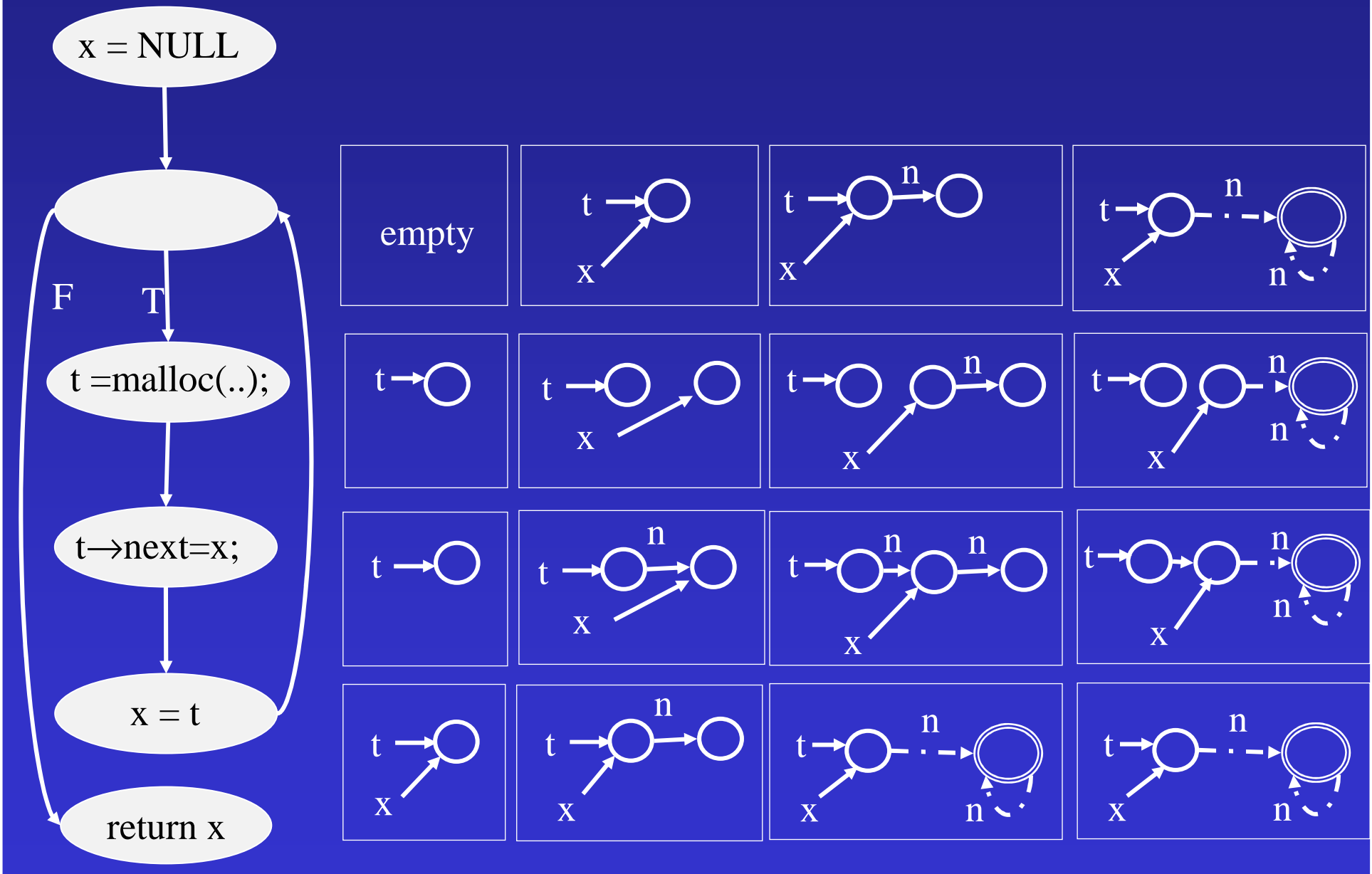
✓ No memory leaks

✓ Returns acyclic list

# Example: Collecting Interpretation



# Example: Abstract Interpretation





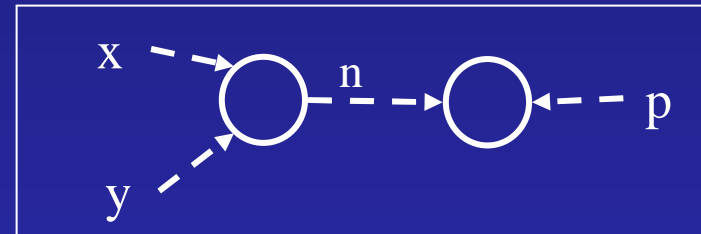
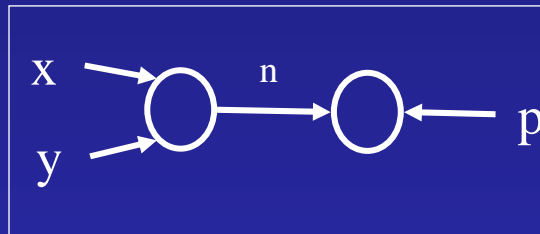
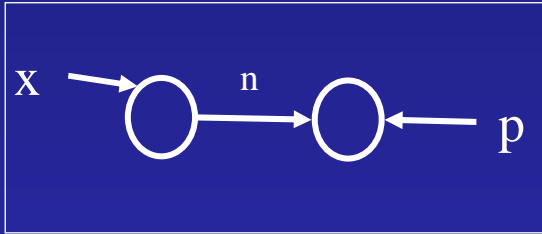
# Challenge 1 - Memory Allocation

- The number of allocated objects/threads is not known
- Concrete state space is infinite
- How to guarantee termination?

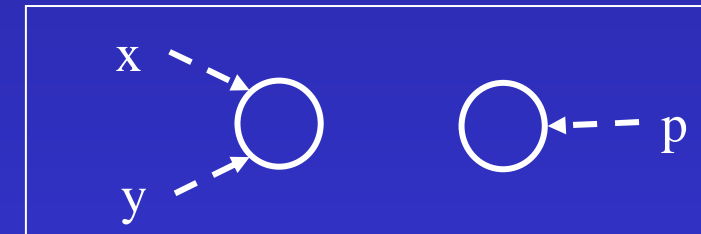
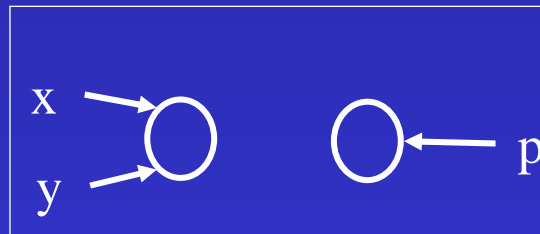
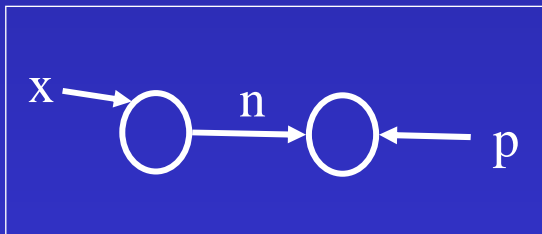
## Challenge 2 - Destructive Updates

- The program manipulates states using destructive updates
  - $e \rightarrow \text{next} = t$
- Hard to define concrete interpretation
- Harder to define abstract interpretation

# Challenge 2 - Destructive Update

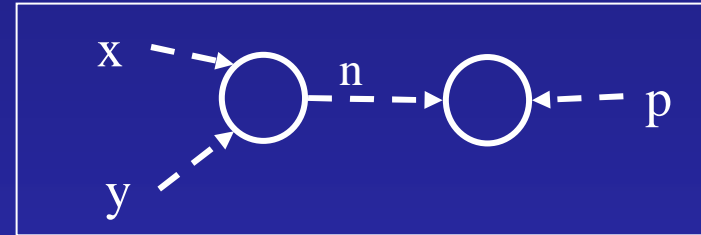


$y \rightarrow \text{next} = \text{NULL}$

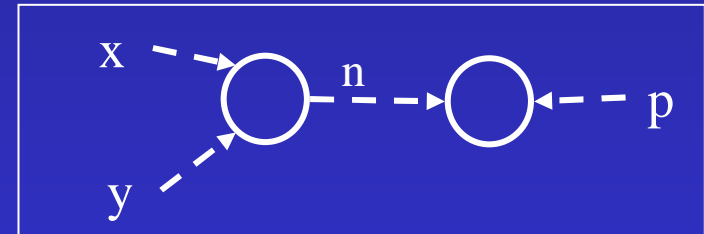


Unsound ☹

# Challenge 2 - Destructive Update



$y \rightarrow \text{next} = \text{NULL}$



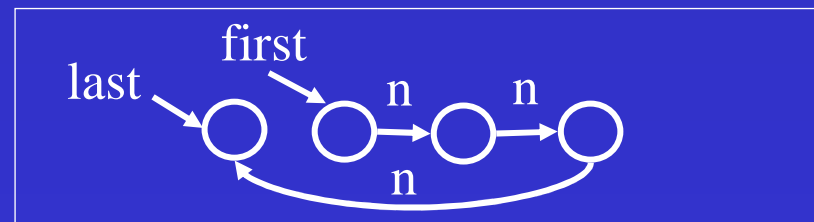
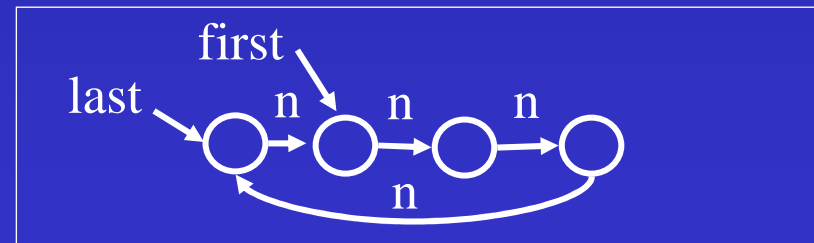
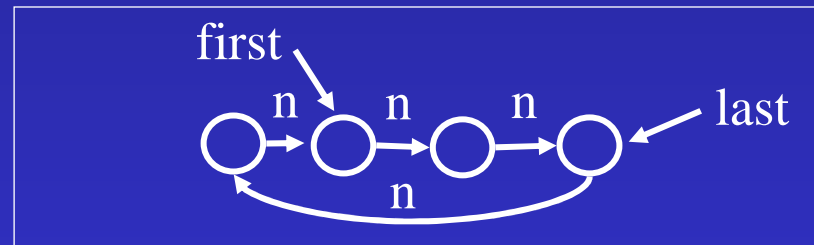
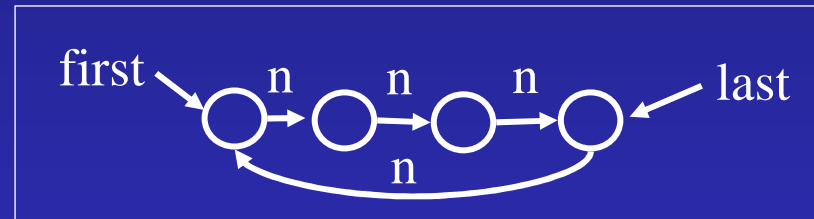
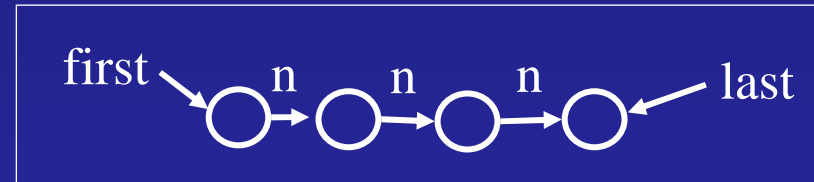
Imprecise ☹

# Challenge 3 – Re-establishing Data Structure Invariants

- Data-structure invariants typically only hold at the beginning and end of ADT operations
- Need to verify that data-structure invariants are re-established

# Challenge 3 – Re-establishing Data Structure Invariants

```
rotate(List first, List last) {  
    if ( first != NULL) {  
        → last → next = first;  
        → first = first → next;  
        → last = last → next;  
        → last → next = NULL;  
    }  
}
```

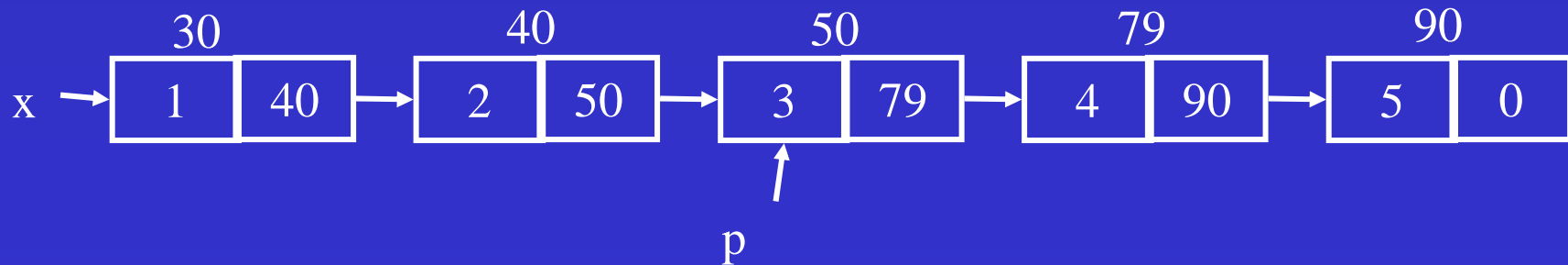


# Plan

- Concrete interpretation
- Canonical abstraction
- Abstract interpretation using canonical abstraction (next lesson)

# Traditional Heap Interpretation

- States = Two level stores
  - Env:  $\text{Var} \rightarrow \text{Values}$
  - fields:  $\text{Loc} \rightarrow \text{Values}$
  - $\text{Values} = \text{Loc} \cup \text{Atoms}$
- Example
  - Env =  $[x \mapsto 30, p \mapsto 79]$
  - next =  $[30 \mapsto 40, 40 \mapsto 50, 50 \mapsto 79, 79 \mapsto 90]$
  - val =  $[30 \mapsto 1, 40 \mapsto 2, 50 \mapsto 3, 79 \mapsto 4, 90 \mapsto 5]$



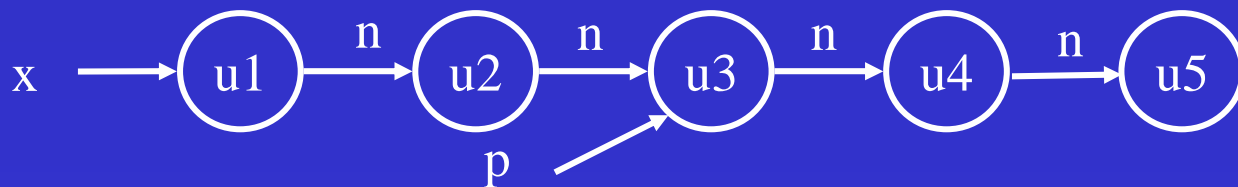


# Predicate Logic

- Vocabulary
  - A finite set of predicate symbols  $P$  each with a fixed arity
- Logical Structures  $S$  provide meaning for predicates
  - A set of individuals (nodes)  $U$
  - $p^S: (U^S)^k \rightarrow \{0, 1\}$
- $\text{FO}^{\text{TC}}$  over TC,  $\forall \exists \neg \wedge \vee$  express logical structure properties

# Representing Stores as Logical Structures

- Locations  $\approx$  Individuals
- Program variables  $\approx$  Unary predicates
- Fields  $\approx$  Binary predicates
- Example
  - $U = \{u1, u2, u3, u4, u5\}$
  - $x = \{u1\}$ ,  $p = \{u3\}$
  - $next = \{\langle u1, u2 \rangle, \langle u2, u3 \rangle, \langle u3, u4 \rangle, \langle u4, u5 \rangle\}$



# Formal Semantics of First Order Formulae

- For a structure  $S = \langle U^S, p^S \rangle$
- Formulae  $\varphi$  with LVar free variables
- Assignment  $z: \text{LVar} \rightarrow U^S$
- $\llbracket \varphi \rrbracket^S(z): \{0, 1\}$

$$\llbracket 1 \rrbracket^S(z) = 1$$

$$\llbracket 0 \rrbracket^S(z) = 0$$

$$\llbracket p(v_1, v_2, \dots, v_k) \rrbracket^S(z) = p^S(z(v_1), z(v_2), \dots, z(v_k))$$

# Formal Semantics of First Order Formulae

- For a structure  $S = \langle U^S, p^S \rangle$
- Formulae  $\varphi$  with LVar free variables
- Assignment  $z: \text{LVar} \rightarrow U^S$
- $\llbracket \varphi \rrbracket^S(z): \{0, 1\}$

$$\llbracket \varphi_1 \vee \varphi_2 \rrbracket^S(z) = \max (\llbracket \varphi_1 \rrbracket^S(z), \llbracket \varphi_2 \rrbracket^S(z))$$

$$\llbracket \varphi_1 \wedge \varphi_2 \rrbracket^S(z) = \min (\llbracket \varphi_1 \rrbracket^S(z), \llbracket \varphi_2 \rrbracket^S(z))$$

$$\llbracket \neg \varphi_1 \rrbracket^S(z) = 1 - \llbracket \varphi_1 \rrbracket^S(z)$$

$$\llbracket \exists v: \varphi_1 \rrbracket^S(z) = \max \{ \llbracket \varphi_1 \rrbracket^S(z[v \mapsto u]) : u \in U^S \}$$

# Formal Semantics of Transitive Closure

- For a structure  $S = \langle U^S, p^S \rangle$
- Formulae  $\varphi$  with LVar free variables
- Assignment  $z: \text{LVar} \rightarrow U^S$
- $\llbracket \varphi \rrbracket^S(z): \{0, 1\}$

$$\llbracket p^*(v_1, v_2) \rrbracket^S(z) = \max \{ u_1, \dots, u_k \in U, Z(v_1)=u_1, Z(v_2)=u_2 \} \min \{ 1 \leq i < k \} p^S(u_i, u_{i+1})$$

## Concrete Interpretation Rules (Pnueli)

Statement	Safety Precondition	Postcondition
$x = \text{NULL}$	1	$x' = \lambda v. 0$
$x = \text{malloc}()$	$\exists v_0: \neg \text{active}(v_0)$	$x' = \lambda v. \text{eq}(v, v_0)$ $\text{active}' = \lambda v. \text{active}(v) \vee \text{eq}(v, v_0)$
$x = y$	1	$x' = \lambda v. y(v)$
$x = y \rightarrow \text{next}$	$\exists v_0: y(v_0) \wedge \text{active}(v_0)$	$x' = \lambda v. \text{next}(v_0, v)$
$x \rightarrow \text{next} = y$	$\exists v_0: x(v_0) \wedge \text{active}(v_0)$	$\text{next}' = \lambda. v_1, v_2. \neg \text{eq}(v_1, v_0) \wedge \text{next}(v_1, v_2) \vee \text{eq}(v_1, v_0) \wedge y(v_2)$

# Invariants

- No memory leaks

$$\forall v: \text{active}(v) \rightarrow \bigvee_{\{x \in \text{PVar}\}} \exists v_1: x(v_1) \wedge \text{next}^*(v_1, v)$$

- Acyclic list(x)

$$\forall v_1, v_2: x(v_1) \wedge \text{next}^*(v_1, v_2) \rightarrow \neg \text{next}^+(v_2, v_1)$$

- Reverse (x)

$$\forall v_1, v_2, v_3: x(v_1) \wedge \text{next}^*(v_1, v_2) \rightarrow \\ \text{next}(v_2, v_3) \leftrightarrow \text{next}'(v_3, v_2)$$

## Why use logical structures?

- Naturally model pointers and dynamic allocation
- No a priori bound on number of locations
- Use formulas to express semantics
- Indirect store updates using quantifiers
- Can model other features
  - Concurrency
  - Abstract fields



## Why use logical structures?

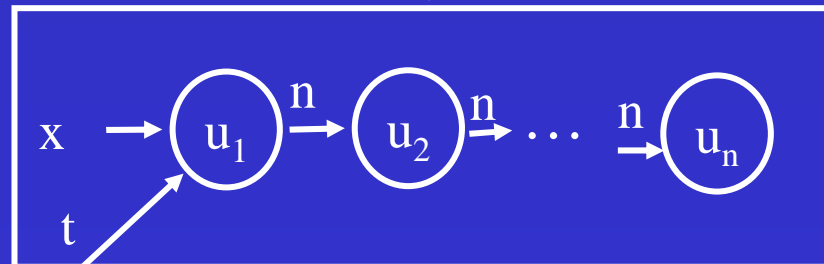
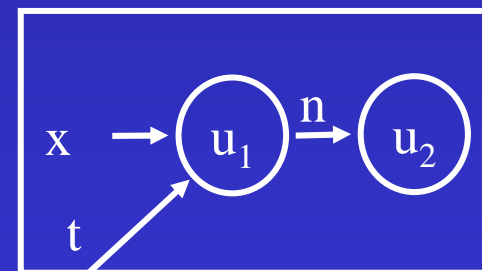
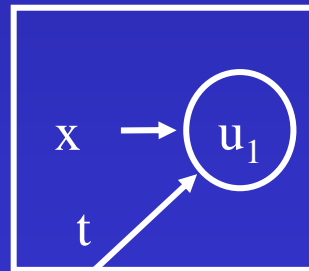
- Behaves well under abstraction
- Enables automatic construction of abstract interpreters from concrete interpretation rules (TVLA)

# Collecting Interpretation

- The set of reachable logical structures in every program point
- Statements operate on sets of logical structures
- Cannot be directly computed for programs with unbounded store and loops

```
x = NULL;  
while (...) do {  
    t = malloc();  
    t → next = x;  
    x = t  
}
```

empty



# Plan

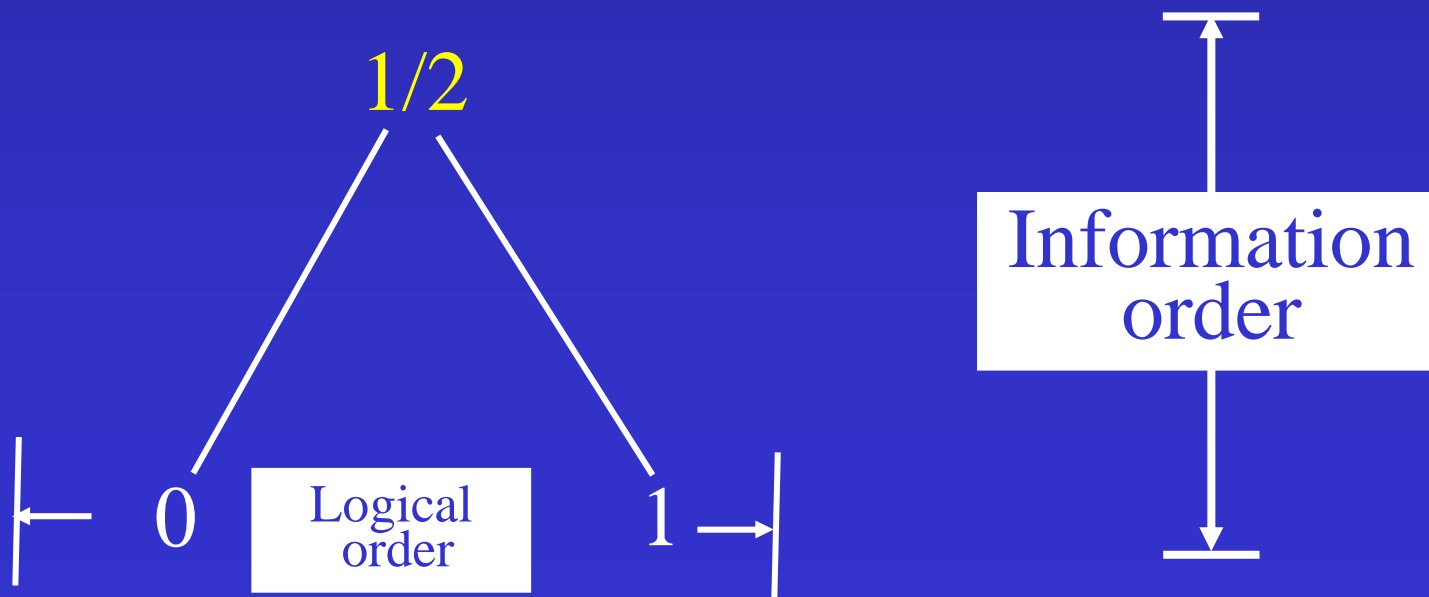
- Concrete interpretation
- Canonical abstraction

# Canonical Abstraction

- Convert logical structures of unbounded size into bounded size
- Guarantees that number of logical structures in every program is finite
- Every first-order formula can be conservatively interpreted

# Kleene Three-Valued Logic

- 1: True
- 0: False
- $1/2$ : Unknown
- A join semi-lattice:  $0 \sqcup 1 = 1/2$



# Boolean Connectives [Kleene]

$\wedge$	0	1/2	1
0	0	0	0
1/2	0	1/2	1/2
1	0	1/2	1

$\vee$	0	1/2	1
0	0	1/2	1
1/2	1/2	1/2	1
1	1	1	1

# 3-Valued Logical Structures

- A set of individuals (nodes)  $U$
- Predicate meaning
  - $p^S: (U^S)^k \rightarrow \{0, 1, 1/2\}$

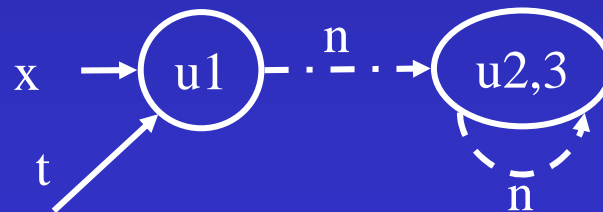
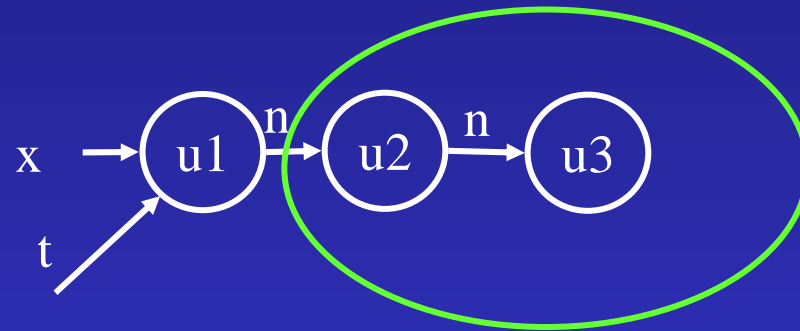
# Canonical Abstraction

- Partition the individuals into **equivalence classes** based on the values of their unary predicates
  - Every individual is mapped into its equivalence class
- Collapse predicates via  $\sqcup$ 
  - $p^S(u'_1, \dots, u'_k) = \sqcup \{p^B(u_1, \dots, u_k) \mid f(u_1)=u'_1, \dots, f(u_k)=u'_k\}$
- At most  $2^A$  abstract individuals



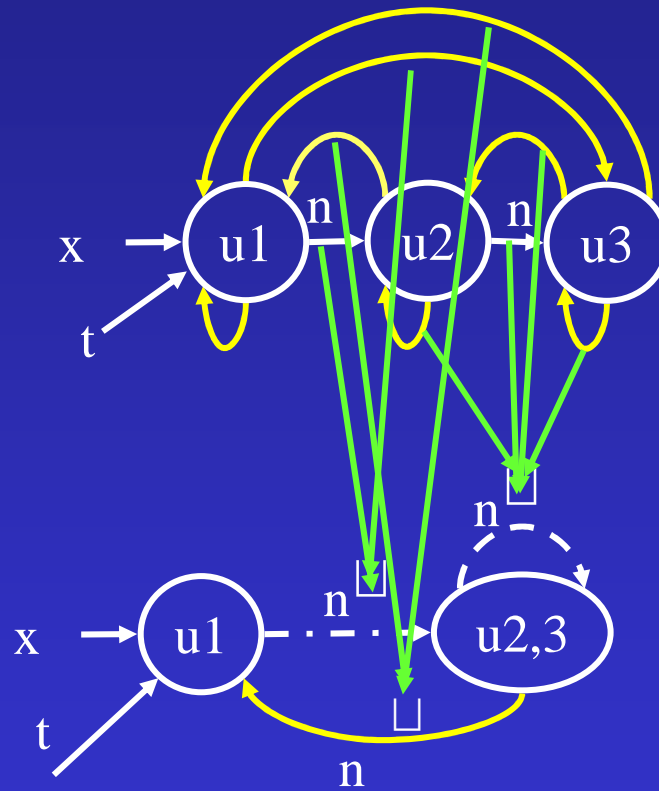
# Canonical Abstraction

```
x = NULL;  
while (...) do {  
    t = malloc();  
    t ->next=x;  
    x = t  
}
```



# Canonical Abstraction

```
x = NULL;  
while (...) do {  
    t = malloc();  
    t ->next=x;  
    x = t  
}
```

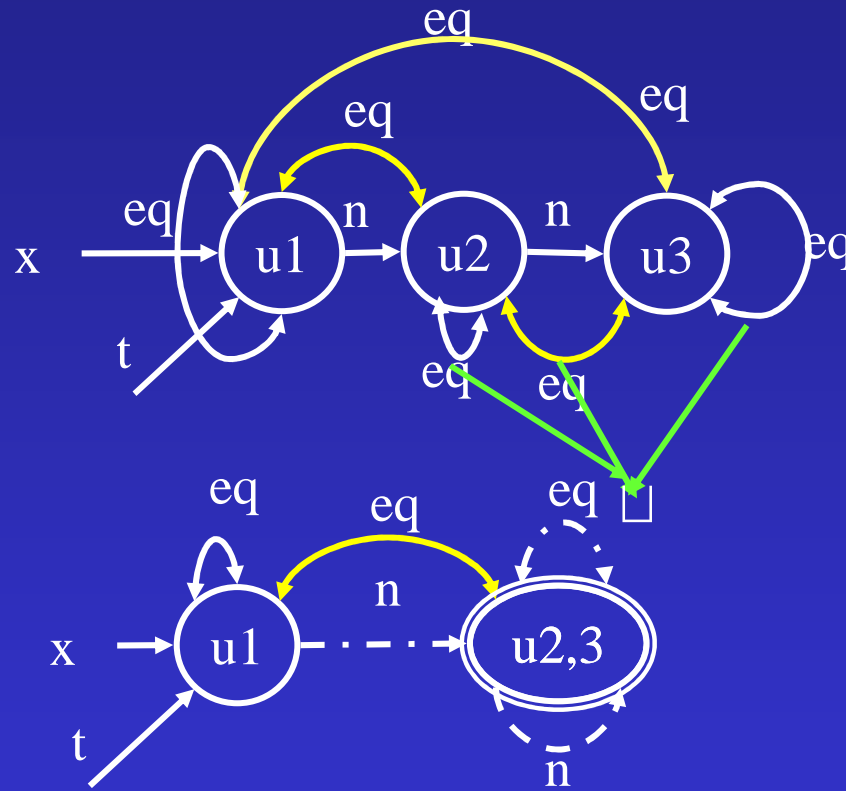


# Canonical Abstraction and Equality

- **Summary nodes** may represent more than one element
- (In)equality need not be preserved under abstraction
- Explicitly record equality
- Summary nodes are nodes with  $eq(u, u)=1/2$

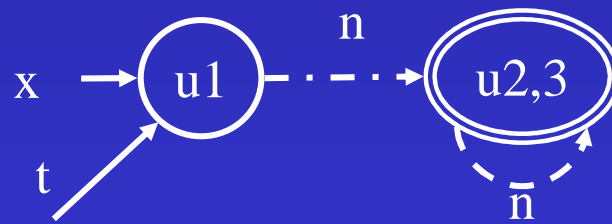
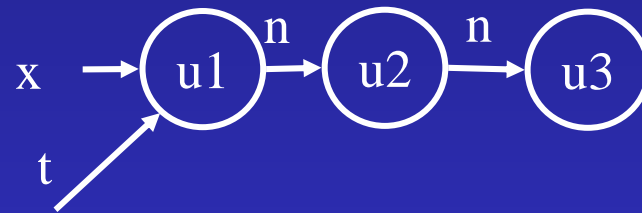
# Canonical Abstraction and Equality

```
x = NULL;  
while (...) do {  
    t = malloc();  
    t ->next=x;  
    x = t  
}
```



# Canonical Abstraction

```
x = NULL;  
while (...) do {  
    t = malloc();  
    t ->next=x;  
    x = t  
}
```



# Summary

- Canonical abstraction guarantees finite number of structures
- The concrete location of an object plays no significance
- But what is the significance of 3-valued logic?

# Summary

- The embedding theorem eliminates the need for proving near commutativity
- Guarantees soundness
- Applied to arbitrary logics
- But can be imprecise