Compilation of certificates

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Motivation

- Mobile code is ubiquitous
 - Large distributed networks of JVM devices
 - aimed at providing a global and uniform access to services
- Security is a central concern:
 - applications manipulate sensitive data stored on devices
 - communications must be secured
- Issues:
 - uniform access to services vs. heterogeneity of devices
 - flexibility of computational infrastructure vs. rigid security architecture
 - platform must be correct (VM, API,...)
 - lack of appropriate security mechanisms to guarantee security on consumer side

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Security challenge



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Downloaded components come equipped with certificates, where certificates:

- are condensed and formalized mathematical proofs/hints
- are self-evident and unforgeable
- can be checked efficiently

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Flavors of Proof Carrying Code



- Application to JVM typing
- On-device checking possible



- Original scenario
- Application to type safety and memory safety

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Contents

The objective of the course is to present verification methods for bytecode and relate them to verification methods for source code

- Type system for information flow based confidentiality policies
- Verification condition generator for logical specifications

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Mobius: Mobility, Ubiquity, Security

Main goals:

- develop basic technologies (type systems and logics) for static enforcement of expressive policies at application level:
 - confidentiality, integrity, resource usage
 - logical specifications
- build a Proof Carrying Code infrastructure that integrates these basic technologies
- use proof assistants to achieve the highest guarantees for security mechanisms

Mobius

INRIA ETH Zürich LMU Münich RU Nijmegen U. Edinburgh Chalmers U. Tallinn U. Imperial College UC Dublin U. Warsaw UP Madrid TLS SAP Research France Telecom **Trusted Logic** TU Darmstadt

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The Mobius view



Part 1: Information flow typing

- G. Barthe, D. Naumann and T. Rezk, *Deriving an Information Flow Checker and Certifying Compiler for Java*, Security and Privacy 2006
- G. Barthe, D. Pichardie and T. Rezk, A Certified Lightweight Non-Interference Java Bytecode Verifier, ESOP'07
- G. Barthe, T. Rezk, A. Russo and A. Sabelfeld, *Security of Multi-Threaded Programs by Compilation*, ESORICS'07

"Low-security behavior of the program is not affected by any high-security data." Goguen & Meseguer 1982



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 $\forall s_1, s_2, \ s_1 \sim_L s_2 \land P, s_1 \Downarrow s'_1 \land P, s_2 \Downarrow s'_2 \implies s'_1 \sim_L s'_2$

High = confidential Low = public

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Direct flow

load y_H store x_L return

Indirect flow

load y_H if 5 push 0 store x_L return

Flow via return	Flow via operand stack	
load y_H if 5 push 1 return push 0 return	push 0 push 1 load y_H if 6 swap store x_L return 0	

A program is an array of instructions:

instr ::= prim op primitive operation
 push v push value on top of stack
 load x load value of x on stack
 store x store top of stack in x
 ifeq j conditional jump
 goto j unconditional jump
 return return

where:

- $j \in \mathcal{P}$ is a program point
- $v \in \mathcal{V}$ is a value
- $x \in \mathcal{X}$ is a variable

• States are of the form *(i, ρ, s)* where:

- *i* : \mathcal{P} is the program counter
- $\rho: \mathfrak{X} \to \mathcal{V}$ maps variables to values
- $s: \mathcal{V}^{\star}$ is the operand stack
- Operational semantics is given by rules are of the form

$$\frac{P[i] = ins \quad constraints}{s \rightsquigarrow s'}$$

Evaluation semantics: *P*, μ ↓ ν, *v* iff (1, μ, ε) →* (ν, *v*), where →* is the reflexive transitive closure of →

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$$\begin{split} P[i] &= \mathsf{prim} \ op \qquad n_1 \ \underline{op} \ n_2 = n \\ \hline \langle i, \rho, n_1 :: n_2 :: s \rangle \rightsquigarrow \langle i+1, \rho, n :: s \rangle \\ \hline \frac{P[i] = \mathsf{load} \ x}{\langle i, \rho, s \rangle \rightsquigarrow \langle i+1, \rho, \rho(x) :: s \rangle} \\ \hline \frac{P[i] = \mathsf{ifeq} \ j}{\langle i, \rho, 0 :: s \rangle \rightsquigarrow \langle j, \rho, s \rangle} \\ \hline \frac{P[i] = \mathsf{goto} \ j}{\langle i, \rho, s \rangle \rightsquigarrow \langle j, \rho, s \rangle} \end{split}$$

$$\begin{split} \frac{P[i] = \mathsf{push}\;n}{\overline{\langle i,\rho,s\rangle} \rightsquigarrow \langle i+1,\rho,n :: s\rangle} \\ \frac{P[i] = \mathsf{store}\;x}{\overline{\langle i,\rho,v :: s\rangle} \rightsquigarrow \langle i+1,\rho(x := v),s\rangle} \\ \frac{P[i] = \mathsf{ifeq}\;j \quad n \neq 0}{\overline{\langle i,\rho,n :: s\rangle} \rightsquigarrow \langle i+1,\rho,s\rangle} \\ \frac{P[i] = \mathsf{return}}{\overline{\langle i,\rho,v :: s\rangle} \rightsquigarrow \langle \rho,v\rangle} \end{split}$$

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Policy

- A lattice of security levels $S = \{H, L\}$ with $L \leq H$
- Each program is given a security signature: $\Gamma : \mathfrak{X} \to S$ and k_{ret} .
- Γ determines an equivalence relation \sim_L on memories: $\rho \sim_L \rho'$ iff

$$\forall x \in \mathfrak{X}. \Gamma(x) \leqslant L \Rightarrow \rho(x) = \rho'(x)$$

• Program *P* is *non-interfering* w.r.t. signature Γ , k_{ret} iff for every μ , μ' , ν , ν' , v, v', v, v',

$$\left. \begin{array}{c} P, \mu \Downarrow \nu, v \\ P, \mu' \Downarrow \nu', v' \\ \mu \sim_L \mu' \end{array} \right\} \Rightarrow \nu \sim_L \nu' \wedge (k_{\text{ret}} \leqslant L \Rightarrow v = v')$$

• Transfer rules of the form

 $\frac{P[i] = ins \quad constraints}{i \vdash st \Rightarrow st'} \qquad \frac{P[i] = ins \quad constraints}{i \vdash st \Rightarrow}$

where $st, st' \in S^*$.

• Types assign stack of security levels to program points

$$S: \mathcal{P} \to \mathbb{S}^{\star}$$

•
$$S \vdash P$$
 iff $S_1 = \epsilon$ and for all $i, j \in \mathcal{P}$
• $i \mapsto j \Rightarrow \exists st'. i \vdash S_i \Rightarrow st' \land st' \leqslant S_j;$
• $i \mapsto \Rightarrow i \vdash S_i \Rightarrow$

The transfer rules and typability relation are implicitly parametrized by a signature Γ , k_{ret} and additional information (next slide)

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A program point *j* is in a *control dependence region* of a branching point *i* if

• *j* is reachable from *i*,

• there is a path from *i* to a return point which does not contain *j* CDR can be computed using post-dominators of branching points.

Example :

- *a* must belong to *region*(*i*)
- *b* does not necessary belong to *region*(*i*)



CDR usage : tracking implicit flows

In a typical type system for a structured language:

$$\frac{\vdash exp:k \quad [k_1] \vdash c_1 \quad [k_2] \vdash c_2 \quad k \leq k_1 \quad k \leq k_2}{[k] \vdash \text{if } exp \text{ then } c_1 \text{ else } c_2}$$

In our context

- *se*: a security environment that attaches a security level to each program point
- for each branching point *i*, we constrain se(j) for all $j \in region(i)$

$$\frac{P[i] = \mathsf{ifeq}\; i' \quad \forall j \in \mathit{region}(i), \, k \leqslant \mathit{se}(j)}{i \vdash k :: \mathit{st} \Rightarrow \cdots}$$

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COAP1: for all program points *i* and all successors *j*, *k* of *i* ($i \mapsto j$ and $i \mapsto k$) such that $j \neq k$ (*i* is hence a branching point), $k \in region(i)$ or k = jun(i);

SOAP2: for all program points *i*, *j*, *k*, if $j \in region(i)$ and $j \mapsto k$, then either $k \in region(i)$ or k = jun(i);

SOAP3: for all program points *i*, *j*, if $j \in region(i)$ and $j \mapsto then jun(i)$ is undefined.

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SOAP1: for all program points *i* and all successors *j*, *k* of *i* ($i \mapsto j$ and $i \mapsto k$) such that $j \neq k$ (*i* is hence a branching point), $k \in region(i)$ or k = jun(i);

- SOAP2: for all program points *i*, *j*, *k*, if $j \in region(i)$ and $j \mapsto k$, then either $k \in region(i)$ or k = jun(i);
- SOAP3: for all program points i, j, if $j \in region(i)$ and $j \mapsto$ then jun(i) is undefined.



P[i] = push n	$P[i] = binop \ op$		
$\overline{i \vdash st \Rightarrow se(i) :: st}$	$\overline{i \vdash k_1 :: k_2 :: st \Rightarrow (k_1 \sqcup k_2) :: st}$		
P[i] = load x	P[i] = store x	$se(i) \sqcup k \leqslant \Gamma(x)$	
$\overline{i \vdash st} \Rightarrow (\Gamma(x) \sqcup se(i)) :: st$	$i \vdash k :: st \Rightarrow st$		
P[i] = goto j	P[i] = return	$se(i) \sqcup k \leqslant k_r$	
$i \vdash st \Rightarrow st$	$i \vdash k :: st \Rightarrow$		
P[i] = ifeq j	$\forall j' \in region(i), \ k \leq$	$\leq se(j')$	
$i \vdash k :: \epsilon \Rightarrow \epsilon$			

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Soundness

If $S \vdash P$ (w.r.t. *se* and *cdr*) then *P* is non-interfering.

Proof

Marktoberdorf, August 2007 Compilation

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Soundness

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Lightweight checking algorithm

- Code provided with:
 - regions (verified by a region checker),
 - security environment
 - type annotations for junction points (most often empty)
- Program entry point is typed with the empty stack
- Propagation
 - Pick a program point *i* annotated with *st*
 - Compute st' such that $i \vdash st \Rightarrow st'$. If there is no st', then reject program.
 - If *st*^{*i*} exists, then for all successors *j* of *i*
 - if *j* is not yet annotated, annotated it with *st'*
 - if *j* is annotated with st'', check that $st' \leq st''$. If not, reject program

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- Source information flow type system offers a tool for developing secure applications, but does not directly address mobile code
- Bytecode verifier provides information flow assurance to users
- Reconcile both views by showing that typable programs are compiled into typable programs

$$\forall P, \vdash P \implies \exists S. \ S \vdash \llbracket P \rrbracket$$

Must also compile regions and security environment

• Programs are commands

 $c ::= x := e | if(e){c}{c} | while(e){c} | c; c | skip | return e$

• Security policy $\Gamma : \mathfrak{X} \to \mathfrak{S}$ and k_{ret}

• Volpano-Smith security type system

$$\frac{e:k \quad k \sqcup pc \leqslant \Gamma(x)}{[pc] \vdash x := e} \qquad \frac{[pc] \vdash c \quad [pc] \vdash c'}{[pc] \vdash c; c'} \qquad \overline{[pc] \vdash \mathsf{skip}}$$

$$\frac{e:pc \quad [pc] \vdash c_1 \quad [pc] \vdash c_2}{[pc] \vdash \mathsf{if}(e)\{c_1\}\{c_2\}} \qquad \frac{e:pc \quad [pc] \vdash c}{[pc] \vdash \mathsf{while}(e)\{c\}} \qquad \frac{e:k \quad k \sqcup pc \leqslant k_{\mathsf{ret}}}{[pc] \vdash \mathsf{return } e}$$

$$\frac{[pc] \vdash c \quad pc' \leq pc}{[pc'] \vdash c'} \qquad \qquad \frac{e:k \quad k \leq k'}{e:k'}$$

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Compiler

$$\begin{bmatrix} x \end{bmatrix} = \log x \\ \begin{bmatrix} v \end{bmatrix} = push v \\ \begin{bmatrix} e_1 \ op \ e_2 \end{bmatrix} = \begin{bmatrix} e_2 \end{bmatrix}; \begin{bmatrix} e_1 \end{bmatrix}; \text{ binop } op \\ k: \begin{bmatrix} x := e \end{bmatrix} = \begin{bmatrix} e \end{bmatrix}; \text{ store } x \\ k: \begin{bmatrix} i_1; i_2 \end{bmatrix} = k: \begin{bmatrix} i_1 \end{bmatrix}; k_2: \begin{bmatrix} i_2 \end{bmatrix} \\ \text{where } k_2 = k + |\begin{bmatrix} i_1 \end{bmatrix}| \\ k: \begin{bmatrix} \text{return } e \end{bmatrix} = \begin{bmatrix} e \end{bmatrix}; \text{ return} \\ k: \begin{bmatrix} \text{if}(e_1 \ cmp \ e_2)\{i_1\}\{i_2\} \end{bmatrix} = \begin{bmatrix} e_2 \end{bmatrix}; \begin{bmatrix} e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i_1 \end{bmatrix}; \text{ goto } l; \ k_2: \begin{bmatrix} i_2 \end{bmatrix} \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \begin{bmatrix} e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i_1 \end{bmatrix}; \text{ goto } l; \ k_2: \begin{bmatrix} i_2 \end{bmatrix} \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; + |\begin{bmatrix} e_1 \end{bmatrix}| + 1 \\ k_2 = k_1 + |\begin{bmatrix} i_1 \end{bmatrix}| + 1 \\ l = k_2 + |\begin{bmatrix} i_2 \end{bmatrix}| \\ k: \begin{bmatrix} \text{while}(e_1 \ cmp \ e_2)\{i\} \end{bmatrix} = \begin{bmatrix} e_2 \end{bmatrix}; \begin{bmatrix} e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} i \end{bmatrix}; \text{ goto } k \\ \text{where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ if } cmp \ k_2; k_1: \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k \\ \text{ where } k_1 = k + |\begin{bmatrix} e_2 \end{bmatrix}; \| e_1 \end{bmatrix}; \text{ for } k \\ \text{ where } k_1 = k \\ \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_2 \end{bmatrix}; \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2; k_1: \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2; k_1 \\ \text{ where } k_1 = k \\ \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k \\ \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2; k_1 \\ \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2; k_1 \\ \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2; k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2; k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; \text{ for } k_2 \end{bmatrix} = \begin{bmatrix} e_1 \end{bmatrix}; e_1 \end{bmatrix} = \begin{bmatrix}$$

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 $k_2 = k_1 + |[[i]]| + 1$
Compiler correctness

 $P, \mu \Downarrow \nu, v \text{ implies } \llbracket P \rrbracket, \mu \Downarrow \nu, v$

Consequences:

• Source programs non-interfering iff their compilation is non-interfering

 $\forall P, P \text{ is non-interfering} \iff \llbracket P \rrbracket$ is non-interfering

• Type-preservation entails soundness of source type system:

 $\forall P, \vdash P \implies P \text{ is non-interfering}$

However, preservation of typing is not a consequence of compiler correctness

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Compiling regions and security environment

- Regions are compiled by induction on structure of programs
- Security environment and type annotations computed from typing derivation

if
$$(y_H)$$
{ $x := 1$ }{ $x := 2$ };
 $x' := 3$;
return 2

load y_H	L		e
ifeq 6	L		$H: \epsilon$
push 1	H	$\in region(2)$	e
store x	Η	$\in region(2)$	$H: \epsilon$
goto 8	H	$\in region(2)$	e
push 2	H	$\in region(2)$	e
store x	H	$\in region(2)$	$H: \epsilon$
push 3	L	= jun(2)	e
store x'	L	-	$L: \epsilon$
push 2	L		e
return	L		$L: \epsilon$

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- For our (non-optimizing) compiler: If *P* is typable, then **[***P***]** is typable wrt security environment, regions, and type annotations generated by extended compiler. Furthemore, generated regions satisfy SOAP.
- For optimizing compilers, type preserving compilation may fail:

$$x_H := n_1 * n_2; y_L := n_1 * n_2 \implies x_H := n_1 * n_2; y_L := x_H$$

There may be easy fixes

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- Mobile code applications often exploit concurrency
- Concurrent execution of secure sequential programs is not necessarily secure:

 $if(y_H > 0)$ {skip; skip}{skip}; $x_L := 1$ ||skip; skip; $x_L := 2$

Using round robin scheduler with time slice one:

- if $y_H > 0$ then $x_L := 1$
- if not $y_H > 0$ then $x_L := 2$
- Security of multi-threaded programs can be achieved:
 - by imposing strong security conditions on programs
 - by relying on secure schedulers

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A secure scheduler selects the thread to be executed in function of the security environment:

- the thread pool is partitioned into low, high, and hidden threads
- if a thread is hidden (currently executing under the scope of a high branching instruction), then only high threads are scheduled
- if the program counter of the last executed thread becomes high (resp. low), then the thread becomes hidden or high (resp. low)

Round-robin schedulers are secure, provided they take over control when threads become high/low/hidden

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- Instruction for dynamic thread creation start *i*
- States $\langle \rho, \lambda \rangle$ where λ associates to each active thread a pair $\langle i, s \rangle$.
- Semantics lifted from sequential fragment

	$ \begin{array}{ll} pickt(\langle \rho, \lambda \rangle, h) = ctid & \lambda(ctid) = \langle i, s \rangle \\ P[i] \neq start k & \langle i, \rho, s \rangle \leadsto_{seq} \langle i', \rho', s' \rangle \end{array} $				
	$\langle ho,\lambda angle \rightsquigarrow \langle ho',\lambda' angle$				
where	$\lambda'(tid) = \begin{cases} \langle i', s' \rangle & \text{if } tid = ctid \\ \lambda(tid) & \text{otherwise} \end{cases}$				

Policy and type system

- Policy and type system similar to sequential fragment
- Transfer rules inherited from sequential fragment

$$\frac{P[i] \neq \mathsf{start}\, j \quad i \vdash_{\mathsf{seq}} st \Rightarrow st'}{i \vdash st \Rightarrow st'} \quad \frac{P[i] = \mathsf{start}\, j \quad se(i) \leqslant se(j)}{i \vdash st \Rightarrow st}$$

- Assume the scheduler is secure, type soundness and type preservation can be lifted from sequential language:
 - Type soundness: same proof techniques (using extended SOAP properties)
 - Type preservation: parallel composition typed in the naive way

$$\frac{[pc] \vdash P \qquad [pc] \vdash Q}{[pc] \vdash P ||Q}$$

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compiler generates security environment that prevents internal timing leaks

We have formally proved in Coq the soundness of information flow type system for a sequential JVM-like language, and extracted an information flow checker.

Main issue is with exceptions:

- loss of precision due to explosion of control flow
- regions are parametrized by exceptions
- more complex signatures and typing rules
- for type-preserving compilation, loss of structure at source level

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There are also interesting issues wrt dynamic object creation:

- heap *L*-equivalence
- allocator may leak information

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- preliminary analysis in order to reduce control flow graph
 - null pointers
 - array accesses
 - ...
- CDR analyser computes control dependence regions
- IF (Information Flow) analyser computes a security environment and a type



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Type annotations required on programs:

- $ft: \mathfrak{F} \to \mathfrak{S}$ attaches security levels to fields,
- each method posseses one (or several) signature(s):

$$\vec{k_v} \xrightarrow{k_h} \vec{k_r}$$

- $\vec{k_v}$ provides the security level of the method parameters
- *k_h*: effect of the method on the heap
- $\vec{k_r}$ is a record of security levels of the form $\{n: k_n, e_1: k_{e_1}, \dots, e_n: k_{e_n}\}$
 - *k_n* is the security level of the return value (normal termination),
 - *k_i* is the security level of each exception *e_i* that might be propagated by the method

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General form

 $\frac{P[i] = ins \quad constraints}{\Gamma, ft, region, se, sgn, i \vdash^{\tau} st \Rightarrow st'}$

Invokation

$$\begin{split} P_{m}[i] &= \mathsf{invokevirtual} \ m_{\mathrm{ID}} \qquad \Gamma_{m_{\mathrm{ID}}}[k] = \vec{k'_{a}} \stackrel{k'_{h}}{\longrightarrow} \vec{k'_{r}} \\ k \sqcup k_{h} \sqcup se(i) \leqslant k'_{h} \qquad k \leqslant \vec{k'_{a}}[0] \qquad \forall i \in [0, \mathsf{length}(st_{1}) - 1], \ st_{1}[i] \leqslant \vec{k'_{a}}[i + 1] \\ e \in \mathsf{excAnalysis}(m_{\mathrm{ID}}) \cup \{\mathbf{np}\} \qquad \forall j \in region(i, e), \ k \sqcup \vec{k'_{r}}[e] \leqslant se(j) \qquad \mathsf{Handler}(i, e) = t \\ \hline \Gamma, region, se, \vec{k_{a}} \stackrel{k_{h}}{\longrightarrow} \vec{k_{r}}, i \vdash^{e} st_{1} :: k :: st_{2} \Rightarrow (k \sqcup \vec{k'_{r}}[e]) :: \varepsilon \end{split}$$

other 60 typing rules...

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Example of typable program

else { $y \cdot f = 3;$ };

return 1;

- 1 load x
- 2 ifeq 5

- 4 throw
- 5 load y
- 6 push 3
- 7 putfield f
- 8 push 1
- 9 return

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$$m: (x:L, y:H) \xrightarrow{H} \{\mathbf{n}: H, C:L, \mathbf{np}:H\}$$

• $k_h = H$: no side effect on low fields

int m(boolean x,C y) throws C {
 if (x) {throw new C();}

- $\vec{k_r}[n] = H$: result depends on *y*
- termination by an exception C does not depend on *y*
- but termination by a null pointer exception does

Justifying fine grain treatment of exceptions

try {z = o.m(x,y);} catch (NullPointerException z) {}; t = 1;



Justifying fine grain treatment of exceptions

try {z = o.m(x,y);} catch (NullPointerException z) {}; t = 1;



Naive treatment of exceptions

• [4,5,6] is a high region (depends on y_H): $t_L = 1$ is rejected

Justifying fine grain treatment of exceptions

try {z = o.m(x,y);} catch (NullPointerException z) {}; t = 1;

 $\begin{array}{l} 0: \text{load } o_L \\ 1: \text{load } y_H \\ 2: \text{load } x_L \\ 3: \text{invokevirtual } m \\ 4: \text{store } z_H \\ 5: \text{push } 1 \\ 6: \text{store } t_L \\ \text{handler}: [0, 3], \text{NullPointer} \rightarrow 4 \end{array}$

Treating each exception separately

• [4,5,6] is a low region: $t_L = 1$ is accepted



- We have developed:
 - Sound information flow bytecode verifier for sequential fragment of JVM
 - Type-preserving compiler for Java
- Next goal is to provide support for realistic applications:
 - more flexible type system
 - more flexible policies
 - Trusted declassifier
 - Cryptography
- Other goals
 - certifying compilation
 - distribution by compilation



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Declassification (from A. Sabelfeld)



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Final remarks on machine-checked proofs

- Implementing an information flow type checker for JVM is a non-trivial task
- Do you trust your implementation? Do you trust the non-interference proof?
- We have used the Coq proof assistant
 - to formally define non-interference,
 - to formally specify information flow type system,
 - to mechanically prove that typability enforces non-interference,
 - to program a type checker and prove it enforces typability,
 - to extract an Ocaml implementation of this type checker.

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Machine-checked proof: structure

- Basis : JVM program and small-step semantics formalisation (Bicolano)
- Intermediate semantics:
 - operates on annotated programs
 - method calls are big-step (simpler definition of ~_L without callstacks; inappropriate for multi-threading)
- Implementation and correctness proof of the CDR checker
- Implementation and correctness proof of the information flow type system

Human effort

- about 20,000 lines of definitions and proofs with a reasonable Coq style programming,
- about 3,000 lines are only there to define the JVM semantics

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Architecture revisited

Since we prove these checkers in Coq, TCB is in fact relegated to Coq and the formal definition of non-interference.



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Architecture revisited

Since we prove these checkers in Coq, TCB is in fact relegated to Coq and the formal definition of non-interference.



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Architecture revisited

Since we prove these checkers in Coq, TCB is in fact relegated to Coq and the formal definition of non-interference.

- Similar to Appel's Foundational PCC
- We exploit reflection to achieve small certificates



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Compilation of certificates

Gilles Barthe

INRIA Sophia-Antipolis Méditerranée, France

Part 2: Verification condition generation

- G. Barthe, T. Rezk and A. Saabas, Preservation of proof obligations, FAST'05
- G. Barthe, B. Grégoire and M. Pavlova, Preservation of proof obligations for Java, 2007
- G. Barthe, B. Grégoire, C. Kunz and T. Rezk, Certificate translation for optimizing compilers, SAS'06

Motivation: source code verification

Traditional PCC



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Motivation: source code verification

Source Code Verification



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Motivation: source code verification

Certificate Translation



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Certificate translation vs certifying compilation





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Conventional PCC		Certificate Translation	
Automatically inferred invariants	Specification	Interactive	
Automatic certifying compiler	Verification	Interactive source verification	
Safety	Properties	Complex functional properties	

Certificate translation vs certified compilation

Certified compilation aims at producing a proof term H such that

$$\boldsymbol{H}: \forall \boldsymbol{P} \mid \boldsymbol{\mu} \mid \boldsymbol{\nu}, \mid \boldsymbol{P}, \boldsymbol{\mu} \Downarrow \boldsymbol{\nu} \implies \llbracket \boldsymbol{P} \rrbracket, \boldsymbol{\mu} \Downarrow \boldsymbol{\nu}$$

Thus, we can build a proof term $H' : \{\phi\}\llbracket P \rrbracket \{\psi\}$ from H and $H_0 : \{\phi\}P\{\psi\}$



must be available

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 $\{pre\}$ ins_1 $\{\varphi_1\}$ ins_2

```
\{\varphi_2\}
ins<sub>k</sub>
\{post\}
```

• Assertions: formulae attached to a program point, characterizing the set of execution states at that point.

Instructions are possibly annotated:

ossibly annotated instructions

```
\overline{\mathsf{ins}} ::= \mathsf{ins} \mid \langle arphi, \mathsf{ins} 
angle
```

• A partially annotated program is a triple $\langle P, \Phi, \Psi \rangle$ s.t.

- Φ is a precondition and Ψ is a postcondition
- P is a sequence of possibly annotated instructions

• • • • • • • • • •

 $\{pre\}$ ins₁ $\{\varphi_1\}$ ins₂ \vdots

 ins_k {*post*} • Assertions: formulae attached to a program point, characterizing the set of execution states at that point.

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ins_k {*post*} • Assertions: formulae attached to a program point, characterizing the set of execution states at that point.

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ossibly annotated instructions

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 $\{pre\} \\ ins_1 \\ \{\varphi_1\} \\ ins_2 \\ \vdots \\ \{\varphi_2\} \\ ins_k \\ \{post\} \}$

- Assertions: formulae attached to a program point, characterizing the set of execution states at that point.
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- A partially annotated program is a triple $\langle \textbf{\textit{P}}, \Phi, \Psi \rangle$ s.t.
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A verification Condition Generator (VCGen):

- fully annotates a program
- extracts a set of proof obligations



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Sufficiently annotated program

All infinite paths must go through an annotated program point

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Sufficiently annotated program

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Sufficiently annotated program

All infinite paths must go through an annotated program point



$$\begin{array}{lll} \mathsf{wp}_{\mathcal{L}}(k) &=& \phi & \text{ if } P[k] = \langle \phi, i \rangle \\ \mathsf{wp}_{\mathcal{L}}(k) &=& \mathsf{wp}_i(k) & \text{ otherwise} \end{array}$$

Sufficiently annotated program

All infinite paths must go through an annotated program point



$$\begin{array}{lll} \mathsf{wp}_{\mathcal{L}}(k) &=& \phi & \text{ if } P[k] = \langle \phi, i \rangle \\ \mathsf{wp}_{\mathcal{L}}(k) &=& \mathsf{wp}_i(k) & \text{ otherwise} \end{array}$$

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Sufficiently annotated program

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Annotations do not refer to stacks

Intermediate assertions may do so



- Annotations do not refer to stacks
- Intermediate assertions may do so



- Annotations do not refer to stacks
- Intermediate assertions may do so



- Annotations do not refer to stacks
- Intermediate assertions may do so

$$\begin{cases} true \\ push 5 \\ store x \\ \{x = 5 \} \end{cases} os[\top] = 5$$

- Annotations do not refer to stacks
- Intermediate assertions may do so

{*true*}
push 5 5 = 5
store x os[
$$\top$$
] = 5
{x = 5}

- Annotations do not refer to stacks
- Intermediate assertions may do so

Stack indices

(,)	
{true}	
push 5	5 = 5
store x	os[⊤] = 5
${x = 5}$	

 $k ::= \top | \top - i$

Expressions

 $e ::= res | x^* | x | c | e op e | os[k]$

Assertions

$$\phi ::= e \, cmp \, e \mid \neg \phi \mid \phi \land \phi \mid \phi \lor \phi \mid \phi \Rightarrow \phi$$
$$\forall x. \, \phi \mid \exists x. \, \phi$$

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Weakest precondition

if P[k] = push n then

$$\mathsf{wp}_i(k) = \mathsf{wp}_{\mathcal{L}}(k+1)[n/\mathsf{os}[\top],\top/\top-1]$$

if P[k] = binop op then

 $wp_i(k) = wp_{\mathcal{L}}(k+1)[os(\top - 1) \text{ op } os[\top]/os[\top], \top - 1/\top]$

if P[k] = load x then

$$wp_i(k) = wp_{\mathcal{L}}(k+1)[x/os[\top], \top/\top - 1]$$

if P[k] = store x then

$$\mathsf{wp}_i(k) = \mathsf{wp}_{\mathcal{L}}(k+1)[\mathsf{os}[\top]/x, \top - 1/\top]$$

if P[k] = if cmp / then

$$\begin{aligned} \mathsf{wp}_i(k) &= (\mathsf{os}[\top-1] \mathit{cmp} \, \mathsf{os}[\top] \Rightarrow \mathsf{wp}_{\mathcal{L}}(k+1)[\top-2/\top]) \\ &\wedge (\neg (\mathsf{os}[\top-1] \mathit{cmp} \, \mathsf{os}[\top]) \Rightarrow \mathsf{wp}_{\mathcal{L}}(l)[\top-2/\top]) \end{aligned}$$

• if P[k] = goto I then $wp_i(k) = wp_{\mathcal{L}}(I)$

• if $P[k] = \text{return then wp}_i(k) = \Psi[\text{os}[\top]/\text{res}]$

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Proof obligations $PO(P, \Phi, \Psi)$

• Precondition implies the weakest precondition of entry point:

$$\Phi \Rightarrow \mathsf{wp}_{\mathcal{L}}(1)$$

For all annotated program points (*P*[*k*] = ⟨φ, *i*⟩), the annotation φ implies the weakest precondition of the instruction at *k*:

$$\varphi \Rightarrow \mathsf{wp}_i(k)$$

An annotated program is correct if its verification conditions are valid.

Soundness

Define validity of assertions:

•
$$\boldsymbol{s} \models \phi$$

• $\mu, \mathbf{s} \models \phi$ (shorthand $\mu, \nu \models \phi$ if ϕ does not contain stack indices)

If (P, Φ, Ψ) is correct, and • $P, \mu \Downarrow \nu, v$ • $\mu \models \Phi$ then

$$\mu, \nu \models \Psi[V_{\text{res}}]$$

Furthermore, all intermediate assertions are verified

Proof idea: if $s \rightsquigarrow s'$ and $s \cdot pc = k$ and $s' \cdot pc = k'$,

$$\mu, \mathbf{s} \models \mathsf{wp}_i(k) \implies \mu, \mathbf{s}' \models \mathsf{wp}_{\mathcal{L}}(k')$$

Source language

- Same assertions, without stack expressions
- Annotated programs (P, Φ, Ψ), with all loops annotated while_l(t){s}
- Weakest precondition

$$\overline{\mathsf{wp}_{\mathcal{S}}(\mathsf{skip},\psi) = \psi,\emptyset} \quad \overline{\mathsf{wp}_{\mathcal{S}}(x := e,\psi) = \psi[e/x],\emptyset}$$

$$\frac{\mathsf{wp}_{\mathcal{S}}(i_{t},\psi) = \phi_{t},\theta_{t} \quad \mathsf{wp}_{\mathcal{S}}(i_{f},\psi) = \phi_{t},\theta_{f}}{\mathsf{wp}_{\mathcal{S}}(\mathsf{if}(t)\{i_{t}\}\{i_{f}\},\psi) = (t \Rightarrow \phi_{t}) \land (\neg t \Rightarrow \phi_{t}),\theta_{t} \cup \theta_{f}}$$

$$\frac{\mathsf{wp}_{\mathcal{S}}(i,I) = \phi,\theta}{\mathsf{wp}_{\mathcal{S}}(\mathsf{while}_{I}(t)\{i\},\psi) = I, \{I \Rightarrow ((t \Rightarrow \phi) \land (\neg t \Rightarrow \psi))\} \cup \theta}$$

$$\frac{\mathsf{wp}_{\mathcal{S}}(i_{2},\psi) = \phi_{2},\theta_{2} \quad \mathsf{wp}_{\mathcal{S}}(i_{1},\phi_{2}) = \phi_{1},\theta_{1}}{\mathsf{wp}_{\mathcal{S}}(i_{1};i_{2},\psi) = \phi_{1},\theta_{1} \cup \theta_{2}}$$

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Preservation of proof obligations

Non-optimizing compiler

Syntactically equal proof obligations

 $\mathsf{PO}(P,\phi,\psi) = \mathsf{PO}(\llbracket P \rrbracket,\phi,\psi)$

Marktoberdorf, August 2007 Compilation of certificates

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Non-optimizing compiler

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Adding objects, exceptions, methods

We have formally proved in Coq the soundness of VC generator for a sequential JVM-like language, and proved (almost) PPO for Java

Main points:

- Methods:
 - pre- and post-conditions to ensure modular reasoning
 - behavioral subtyping: method overriding should preserve spec
- Exceptions:
 - loss of precision due to explosion of control flow: preliminary analyses (as in information flow)
 - exceptional postconditions must be considered
- For PPO: renaming, booleans, simple optimizations

However:

- many challenges in verification of sequential OO programs
- concurrency (semantics and verification) is another challenge

Remark on machine-checked proof

- Implementing a verification condition generator for JVM is a non-trivial task
- Do you trust your implementation? And the soundness proof?
- We have used the Coq proof assistant
 - to formally specify the verification condition generator,
 - to mechanically prove that valid proof obligations imply validity of annotations.
- The development is structured in two layers:
 - Basis : JVM program and small-step semantics formalisation (Bicolano)
 - Intermediate semantics:
 - operates on annotated programs
 - method calls are big-step

There is a range of tools that support deductive verification of Java applications. Many tools use JML as specification language.

- Annotation language for Java
- pre- and post-conditions and invariants written as special comments
- Uses Java-like notation
- Annotations are side-effect-free Java expressions + some extra keywords (\exists, \forall, \old(-), \result...)
- Developed by Leavens et.al., Iowa State University
- Different tools available to validate, reason or generate JML annotations

```
/*@ exceptional_behavior
  Q
   requires arg == null;
  ß
      signals (NullPointerException) true;
  @ also
   behavior
  ß
  ß
   requires arg != null;
  ß
   ensures \result == arg[0];
  Q
    signals (IndexOutOfBoundsException)
  ß
                    arg.length == 0;
  @*/
Object firstElement (Object [] arg) {
  return arg[0];
}
```

Many tools to validate Java applications annotated with JML: testing, run-time checking, model-checking...

and deductive verification tools:

- ESC/Java: extended static checking, uses intermediate language (guarded commands)
- JACK: backwards propagation of invariants, support for native methods, support for bytecode (BML)
- Krakatoa/Why: uses intermediate language, also supports C (Caduceus)
- Jive: uses Hoare logic

Also relevant: JSR 308, Spec# for C#

Summary

- We have developed:
 - Sound VC generator for sequential fragment of JVM
 PPO for Java
- Next goal is to provide support for realistic applications:
 - more specification constructs
 - link with JML-based tools
- Other goals
 - certificate generation
 - optimisations
 - concurrency



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Optimizing Compilers



Proofs obligations might not be preserved

- annotations might need to be modified (e.g. constant propagation).
- certificates for analyzers might be needed (certifying analyzer).
- analyses might need to be modified (e.g. dead variable elimination)

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Optimizing Compilers



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Optimizing Compilers



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Certificate Translation with Certifying Analyzers



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Program + Specification

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$$\begin{cases} j = 0 \\ \{j = (b+0) * 0 \land b \le (b+0) \land 0 \le 0 \} \\ i := 0; \\ \{j = (b+i) * i \land b \le (b+i) \land 0 \le i \} \\ x := b+i; \\ \{lnv : j = x * i \land b \le x \land 0 \le i \} \\ while(i! = n) \\ i := c+i \\ j := x * i; \\ \{j = x * i \land b \le x \land 0 \le i \} \\ endwhile; \\ \{n * b \le j \} \end{cases}$$

$$Program \\ Fully Annotated \\ Program \\ Program \\ Fully Annotated \\ Program \\ Full Program$$

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Motivating example

$$\begin{cases} j = 0 \\ \{j = (b+0) * 0 \land b \le (b+0) \land 0 \le 0 \} \\ i := 0; \\ \{j = (b+i) * i \land b \le (b+i) \land 0 \le i \} \\ x := b+i; \\ \{lnv : j = x * i \land b \le x \land 0 \le i \} \\ while(i! = n) \\ i := c+i \\ \{x * i = x * i \land b \le x \land 0 \le i \} \\ j := x * i; \\ \{j = x * i \land b \le x \land 0 \le i \} \\ endwhile; \\ \{n * b \le j \} \\ \end{cases}$$

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Motivating example



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Motivating example

$$\begin{cases} j = 0 \\ \{j = (b + 0) * 0 \land b \le (b + 0) \land 0 \le 0 \\ i := 0; \\ \{j = (b + i) * i \land b \le (b + i) \land 0 \le i \\ x := b + i; \\ \{lm: j = x * i \land b \le x \land 0 \le i \\ while (il = n) \\ \{x * (c + i) = x * (c + i) \land b \le x \land 0 \le c + i \\ j := x * i; \\ endwhile; \\ \{n * b \le j \} \end{cases}$$

Set of Proof Obligations:

•
$$j = 0 \Rightarrow j = (b+0) * 0 \land b \le (b+0) \land 0 \le 0$$

• $j = x * i \land b \le x \land 0 \le i \land i \ne n \Rightarrow$
 $x * (c+i) = x * (c+i) \land b \le x \land 0 \le c+i$
• $j = x * i \land b \le x \land 0 \le i \land i = n \Rightarrow n * b \le j$

Constant propagation analysis

	$\{j = 0\}$
	i := 0;
$(i, 0) \rightarrow$	x := b + i;
	$\{Inv: j = x * i \land b \le x \land 0 \le i\}$
$(x, b) \rightarrow$	while($i! = n$)
$(x,b) \rightarrow$	i := c + i
$(x,b) \rightarrow$	j:=x*i;
	endwhile;
	$\{n * b \le j\}$

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Program transformation

 $\{i = 0\}$ i := 0; $(i, 0) \rightarrow x := b;$ $\{Inv: j = x * i \land b < x \land 0 < i\}$ $(x, b) \rightarrow \text{while}(i! = n)$ $(x,b) \rightarrow i := c + i$ $(x, b) \rightarrow j := x * i;$ endwhile; $\{n * b < j\}$

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Program transformation

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 $\{i = 0\}$ i := 0: $\{j = b * i \land b \leq b \land 0 \leq i\}$ $(i, 0) \rightarrow \mathbf{x} := \mathbf{b};$ { Inv : $j = x * i \land b < x \land 0 < i$ } $(x, b) \rightarrow \text{while}(i! = n)$ $(x, b) \rightarrow i := c + i$ $(x, b) \rightarrow j := b * i;$ endwhile; $\{n * b < j\}$

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```
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               i := 0:
               \{i = b * i \land b < b \land 0 < i\}
 (i, 0) \rightarrow \mathbf{x} := \mathbf{b};
           { Inv : j = x * i \land b < x \land 0 < i }
(x, b) \rightarrow \text{while}(i! = n)
(x, b) \rightarrow i := c + i
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(x, b) \rightarrow j := b * i;
               \{j = x * i \land b < x \land 0 < i\}
               endwhile:
               \{n * b < j\}
```

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 (i, 0) \rightarrow \mathbf{x} := \mathbf{b};
           { Inv : j = x * i \land b < x \land 0 < i }
(x, b) \rightarrow \text{while}(i! = n)
(x,b) \rightarrow i := c + i
           \{b * i = x * i \land b < x \land 0 < i\}
(x, b) \rightarrow j := b * i;
              \{j = x * i \land b < x \land 0 < i\}
               endwhile:
               \{n * b < j\}
```

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```
\{i = 0\}
               \{j = b * 0 \land b \le b \land 0 \le 0\}
               i := 0:
              \{i = b * i \land b \leq b \land 0 \leq i\}
 (i, 0) \rightarrow \mathbf{x} := \mathbf{b};
          { Inv : j = x * i \land b < x \land 0 < i }
(x, b) \rightarrow \text{while}(i! = n)
            \{b * (c+i) = x * (c+i) \land b < x \land 0 < c+i\}
(x, b) \rightarrow i := c + i
           \{b * i = x * i \land b < x \land 0 < i\}
(x, b) \rightarrow j := b * i;
              \{j = x * i \land b < x \land 0 < i\}
               endwhile:
               \{n * b < j\}
```

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Proof Obligations

$$\begin{cases} j = 0 \\ \{j = b \\ i = 0; \\ \{j = b * i \land b \le b \land 0 \le 0 \} \\ i := 0; \\ \{j = b * i \land b \le b \land 0 \le i \} \\ x := b; \\ \{lnv: j = x * i \land b \le x \land 0 \le i \} \\ while(il = n) \\ \{b * (c + i) = x * (c + i) \land b \le x \land 0 \le c + i \} \\ i := c + i \\ \{b * i = x * i \land b \le x \land 0 \le i \} \\ j := b * i; \\ i = x + i \land b \le x \land 0 \le i \} \\ endwhile; \\ endwhile; \\ \{n * b \le j \} \end{cases}$$

Proof Obligations:

Proof Obligations

$$\begin{cases} j = 0 \\ \{j = b \ : \ 0 \land b \le b \land 0 \le 0 \\ i := 0; \\ \{j = b \ : \ \wedge b \le b \land 0 \le i \} \\ x := b; \\ \{lnv: j = x \ : \ h \land b \le x \land 0 \le i \} \\ while(il = n) \\ \{b \ : \ (c + i) = x \ : \ (c + i) \land b \le x \land 0 \le c + i \} \\ i := c + i \\ \{b \ : \ i = x \ : \ i \land b \le x \land 0 \le i \} \\ j := b \ : i \\ \{j = x \ : \ i \land b \le x \land 0 \le i \} \\ endwhile; \\ \{n \ \ast b \le j \}$$

Proof Obligations:

 $\begin{array}{l} \bullet j = 0 \Rightarrow j = b * 0 \land b \leq b \land 0 \leq 0 \\ \bullet j = x * i \land b \leq x \land 0 \leq i \land i \neq n \\ \Rightarrow b * (c+i) = x * (c+i) \land b \leq x \land 0 \leq c+i \\ \bullet j = x * i \land b \leq x \land 0 \leq i \land i = n \Rightarrow n * b \leq j \\ \bullet j = x * i \land b \leq x \land 0 \leq i \land i = n \Rightarrow n * b \leq j \\ x = b \end{array}$

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Proof Obligations

$$\begin{cases} j = 0 \\ \{j = b \\ i = b; \\ 0 > i > 0, \\ i = 0; \\ \{j = b * i \land b \le b \land 0 \le i \} \\ x := b; \\ \{lmv; j = x * i \land b \le x \land 0 \le i \land x = b \} \\ while(il = n) \\ \{b * (c + i) = x * (c + i) \land b \le x \land 0 \le c + i \} \\ i := c + i \\ \{b * i = x * i \land b \le x \land 0 \le i \} \\ j := b * i; \\ \{j = x * i \land b \le x \land 0 \le i \} \\ endwhile; \\ endwhile; \\ \{n * b \le j \} \end{cases}$$

Proof Obligations:

 $j = 0 \Rightarrow j = b * 0 \land b \le b \land 0 \le 0$ $j = x * i \land b \le x \land 0 \le i \land x = b \land i \ne n$ $\Rightarrow b * (c+i) = x * (c+i) \land b \le x \land 0 \le c+i$ str an

Solution: strengthen annotations

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allows to verify proof obligations of original program

but also introduces new proof obligations



If the analysis is correct,

• $\psi_1 \Rightarrow \mathsf{wp}(S_1,\psi_2)$

• $\psi_2 \Rightarrow wp(S_2, \psi_3)$

are valid proof obligations.

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- allows to verify proof obligations of original program
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A (1) > A (1) > A

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are valid proof obligations.

Certifying/Proof producing analyzer

A certifying analyzer extends a standard analyzer with a procedure that generates a certificate for the result of the analysis

Certifying analyzers exist under mild hypotheses:

- results of the analysis expressible as assertions
- abstract transfer functions are correct w.r.t. wp
- . . .
- Ad hoc construction of certificates yields compact certificates

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A certifying analyzer extends a standard analyzer with a procedure that generates a certificate for the result of the analysis

- Certifying analyzers exist under mild hypotheses:
 - results of the analysis expressible as assertions
 - abstract transfer functions are correct w.r.t. wp
 - . . .
- Ad hoc construction of certificates yields compact certificates

Certifying analysis for constant propagation

```
{true}
\{b = b\}
i := 0:
\{b = b\}
x := b;
\{Inv : x = b\}
while(i! = n)
{x = b}
  i := c + i
{x = b}
  j:=b∗i;
{x = b}
endwhile;
{true}
```

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Certifying analysis for constant propagation

{true} $\{b = b\}$ i := 0: $\{b = b\}$ x := b: $\{Inv : x = b\}$ while(i! = n) ${x = b}$ i := c + i ${x = b}$ j:=b∗i; ${x = b}$ endwhile: {*true*}

With proof obligations: $x = b \land i = n \Rightarrow true$ $x = b \land i \neq n \Rightarrow x = b$ $true \Rightarrow b = b$

$\{\phi_1\}$	+		\rightarrow			
S_1		S_1		S_1	\rightarrow	S_1^O
$\{\phi_2\}$	+		\rightarrow			
S_2		S_2		S_2	\rightarrow	S_2^O
÷	+	÷	\rightarrow	-		÷
S_{n-1}		S_{n-1}		S_{n-1}	\rightarrow	S_{n-1}^O
$\{\phi_n\}$	+		\rightarrow			
S_n		S_n		S_n	\rightarrow	S_n^O

- Specifying and certifying automatically the result of the analysis
- Merging annotations (trivial)
- Merging certificates

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Specifying and certifying automatically the result of the analysis

- Merging annotations (trivial)
- Merging certificates



- Specifying and certifying automatically the result of the analysis
- Ø Merging annotations (trivial)
 - Merging certificates



- Specifying and certifying automatically the result of the analysis
- Ø Merging annotations (trivial)
- Merging certificates

Merging of certificates is not tied to a particular certificate format, but to the existence of functions to manipulate them.

Proof algebra

axiom : $\mathcal{P}(\Gamma; A; \Delta \vdash A)$ ring : $\mathcal{P}(\Gamma \vdash n_1 = n_2)$ if $n_1 = n_2$ is a ring equality intro_{\Rightarrow} : $\mathcal{P}(\Gamma; A \vdash B) \rightarrow \mathcal{P}(\Gamma \vdash A \Rightarrow B)$ elim_{\Rightarrow} : $\mathcal{P}(\Gamma \vdash A \Rightarrow B) \rightarrow \mathcal{P}(\Gamma \vdash A) \rightarrow \mathcal{P}(\Gamma \vdash B)$ elim₌ : $\mathcal{P}(\Gamma \vdash e_1 = e_2) \rightarrow \mathcal{P}(\Gamma \vdash A[e_{/r}]) \rightarrow \mathcal{P}(\Gamma \vdash A[e_{/r}])$ subst : $\mathcal{P}(\Gamma \vdash A) \rightarrow \mathcal{P}(\Gamma[e_{/r}] \vdash A[e_{/r}])$

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We need to build from the original and analysis certificates:

 $\frac{\phi_1 \Rightarrow \mathsf{wp}(S, \phi_2)}{\{\phi_1\}S\{\phi_2\}} \quad \frac{a_1 \Rightarrow \mathsf{wp}(S, a_2)}{\{a_1\}S\{a_2\}}$

the certificate for the optimized program:

 $\phi_1 \wedge a_1 \Rightarrow \mathsf{wp}(S', \phi_2 \wedge a_2)$

 $\{\phi_1 \wedge a_1\}S'\{\phi_2 \wedge a_2\}$

by using the gluing lemma

 $\forall \phi, \mathsf{wp}(\mathsf{ins}, \phi) \land a \Rightarrow \mathsf{wp}(\mathsf{ins}', \phi)$

where ins' is the optimization of ins, and a is the result of the analysis

We really construct by well-founded induction a proof term of

 $wp_P(k) \wedge a(k) \implies wp_{P'}(k)$

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 $\operatorname{wp}_P(k) \wedge a(k) \Longrightarrow \operatorname{wp}_{P'}(k)$

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 $\frac{\phi_1 \Rightarrow \mathsf{wp}(S, \phi_2)}{\{\phi_1\}S\{\phi_2\}} \quad \frac{a_1 \Rightarrow \mathsf{wp}(S, a_2)}{\{a_1\}S\{a_2\}}$

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by using the gluing lemma

```
\forall \phi, wp(ins, \phi) \land a \Rightarrow wp(ins', \phi)
```

where ins' is the optimization of ins, and a is the result of the analysis

We really construct by well-founded induction a proof term of

 $\mathsf{wp}_{P}(k) \land a(k) \implies \mathsf{wp}_{P'}(k)$

Illustrating: $\forall \phi$, wp(ins, ϕ) $\land a \Rightarrow$ wp(ins', ϕ)

If the value of *e* is known to be *n*, then



The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid n = ethe weakest precondition applied to the transformed instruction work (m, n) = (m, n)

can be derived from the original one:

$\mathsf{wp}(\boldsymbol{y} := \boldsymbol{e}, \boldsymbol{\varphi}) \mid (\equiv \boldsymbol{\varphi}[\boldsymbol{\mathcal{Y}}])$

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Illustrating: $\forall \phi, wp(ins, \phi) \land a \Rightarrow wp(ins', \phi)$

If the value of *e* is known to be *n*, then



The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid n = ethe weakest precondition applied to the transformed instruction work (-n, n) = (-n/2n)

can be derived from the original one:

$\mathsf{wp}(\boldsymbol{y} := \boldsymbol{e}, \boldsymbol{\varphi}) \mid (\equiv \boldsymbol{\varphi}[\boldsymbol{\mathcal{Y}}])$

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If the value of *e* is known to be *n*, then



The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid n = ethe weakest precondition applied to the transformed instruction work $x = n \cdot o$. (= e(2a)

can be derived from the original one:

$\mathsf{wp}(\boldsymbol{y} := \boldsymbol{e}, \boldsymbol{\varphi}) \mid (\equiv \boldsymbol{\varphi}[\boldsymbol{\mathcal{Y}}])$

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If the value of *e* is known to be *n*, then

 $y := e \xrightarrow{n=e} y := n$

The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid n = e

the weakest precondition applied to the transformed instruction

 $\mathsf{wp}(y := n, \varphi) \quad (\equiv \varphi[/y])$

can be derived from the original one:

 $wp(y := e, \varphi) \quad (\equiv \varphi[\overset{e}{/}_{y}])$

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If the value of *e* is known to be *n*, then

 $y := e \xrightarrow{n=e} y := n$

The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid n = ethe weakest precondition applied to the transformed instruction

 $wp(y := n, \varphi) \quad (\equiv \varphi[/y])$

can be derived from the original one:

 $wp(y := e, \varphi) \quad (\equiv \varphi[\overset{e}{/}_{y}])$

A (1) > A (1) > A

If the value of *e* is known to be *n*, then

 $y := e \xrightarrow{n=e} y := n$

The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid n = ethe weakest precondition applied to the transformed instruction

 $\mathsf{wp}(\mathbf{y} := \mathbf{n}, \varphi) \quad (\equiv \varphi[\overset{n}{/}_{y}])$

can be derived from the original one:

 $wp(y := e, \varphi) \quad (\equiv \varphi[\overset{e}{/}_{y}])$

$\{\varphi_1\}$	
x := 5;	
$\{\varphi_2\}$	
у := х	
$\{\varphi_3\}$	

Original PO's:	Analysis PO's :	
• $\varphi_1 \Rightarrow \varphi_2[\frac{5}{x}]$	• true $\Rightarrow 5 = 5$	
• $\varphi_2 \Rightarrow \varphi_3[x/y]$	• $x = 5 \Rightarrow x = 5$	

Original and new proof obligations differ

With the gluing lemma ($\forall \phi, e.x = e \land \phi[\]_y] \Rightarrow \phi[\]_y]$, the original PO entails the new PO

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$\{\varphi_1\}$	
x := 5;	
$\{\varphi_2\}$	
y := x	
$\{\varphi_3\}$	

{true} x := 5; $\{x = 5\}$ y := x $\{x = 5\}$ $\{\varphi_1 \land \text{true}\}$ x := 5; $\{\varphi_2 \land x = 5\}$ y := 5 $\{\varphi_3 \land x = 5\}$

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Original PO's:	Analysis PO's :	Final PO's:
• $\varphi_1 \Rightarrow \varphi_2[\frac{5}{x}]$	• true \Rightarrow 5 = 5	• $\varphi_1 \wedge \text{true} \Rightarrow \varphi_2[\frac{5}{x}] \wedge 5 = 5$
• $\varphi_2 \Rightarrow \varphi_3[x/y]$	• $x = 5 \Rightarrow x = 5$	• $\varphi_2 \wedge x = 5 \Rightarrow \varphi_3[\frac{5}{y}] \wedge x = 5$

Original and new proof obligations differ

With the gluing lemma ($\forall \phi, e.x = e \land \phi[x] \Rightarrow \phi[y]$), the original PO entails the new PO

()	{true}
$\{\varphi_1\}$	x := 5;
x := 5;	$\{x = 5\}$
$\{\varphi_2\}$	y := x
у := х	$\bar{\{x=5\}}$
$\{\varphi_3\}$	(⁻)

$$\{\varphi_1 \land \mathsf{true}\}$$

x := 5;
$$\{\varphi_2 \land x = 5\}$$

y := 5
$$\{\varphi_3 \land x = 5\}$$

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Original PO's:Analysis PO's :Final PO's:•
$$\varphi_1 \Rightarrow \varphi_2[5]_X]$$
• true $\Rightarrow 5 = 5$ • $\varphi_1 \wedge true \Rightarrow \varphi_2[5]_X] \wedge 5 = 5$ • $\varphi_2 \Rightarrow \varphi_3[x]_Y]$ • $x = 5 \Rightarrow x = 5$ • $\varphi_2 \wedge x = 5 \Rightarrow \varphi_3[5]_Y] \wedge x = 5$

Original and new proof obligations differ

With the gluing lemma ($\forall \phi, e.x = e \land \phi[\overset{x}{y}] \Rightarrow \phi[\overset{y}{y}]$), the original PO entails the new PO

C >	{true}	
$\{\varphi_1\}$	x := 5;	
x := 5;	$\{x = 5\}$	
$\{\varphi_2\}$	y := x	
у := х	$\{x = 5\}$	
$\{\varphi_3\}$		

$$\{\varphi_1 \land \mathsf{true}\}$$

x := 5;
$$\{\varphi_2 \land x = 5\}$$

y := 5
$$\{\varphi_3 \land x = 5\}$$

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• $\varphi_1 \Rightarrow \varphi_2[\frac{5}{x}]$	• true \Rightarrow 5 = 5	• $\varphi_1 \wedge \text{true} \Rightarrow \varphi_2[\frac{5}{x}] \wedge 5 = 5$
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Original and new proof obligations differ

With the gluing lemma ($\forall \phi, e.x = e \land \phi[x] \Rightarrow \phi[y]$), the original PO entails the new PO

	{true}	$\{arphi_{1} \wedge true\}$
$\{\varphi_1\}$	x := 5;	x := 5;
x := 5;	$\{x = 5\}$	$\{\varphi_2 \wedge x = 5\}$
$\{\varphi_2\}$	$\mathbf{y} := \mathbf{x}$	y := 5
у := х	$\bar{x} = 5$	$\overline{\{\varphi_3 \land x = 5\}}$
$\{ \varphi_3 \}$	C J	

Original PO's:	Analysis PO's :	Final PO's:
• $\varphi_1 \Rightarrow \varphi_2[\frac{5}{x}]$	• true \Rightarrow 5 = 5	• $\varphi_1 \wedge \text{true} \Rightarrow \varphi_2[\frac{5}{x}] \wedge 5 = 5$
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Original and new proof obligations differ

With the gluing lemma ($\forall \phi, e.x = e \land \phi[\sspace{.5mu}] \Rightarrow \phi[\sspace{.5mu}]$), the original PO entails the new PO

Optimizing compilers try to avoid duplication of computations.

If x already stores the value of e, then

 $\mathbf{y} := \mathbf{e}$ $\mathbf{y} := \mathbf{x}$

The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid x = ethe weakest precondition applied to the transformed instruction

 $\mathsf{wp}(\mathbf{y} := \mathbf{x}, \varphi) \mid (\equiv \varphi[\frac{\mathbf{x}}{2}])$

can be derived from the original one:

 $\mathsf{wp}(\boldsymbol{y} := \boldsymbol{e}, \boldsymbol{\varphi}) \mid (\equiv \boldsymbol{\varphi}[\boldsymbol{\gamma}])$

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Optimizing compilers try to avoid duplication of computations.

If x already stores the value of e, then

 $y := e \xrightarrow{x=\theta} y := x$

The gluing lemma states in this case:

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 $\mathsf{wp}(\mathbf{y} := \mathbf{x}, \varphi) \mid (\equiv \varphi[\mathbf{x}])$

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The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid x = ethe weakest precondition applied to the transformed instruction

 $\mathsf{wp}(y := x, \varphi) \mid (\equiv \varphi[{}^{x}_{y}])$

can be derived from the original one:

 $\mathsf{wp}(y := e, \varphi) \mid (\equiv \varphi[\%]).$

Optimizing compilers try to avoid duplication of computations.

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Optimizing compilers try to avoid duplication of computations.

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The gluing lemma states in this case:

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Optimizing compilers try to avoid duplication of computations.

If x already stores the value of e, then

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The gluing lemma states in this case:

Under the hypothesis that the result of the analysis is valid x = ethe weakest precondition applied to the transformed instruction

 $\mathsf{wp}(\mathbf{y} := \mathbf{x}, \varphi) \quad (\equiv \varphi[\overset{\mathsf{x}}{/}_{y}])$

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 $wp(y := e, \varphi) \quad (\equiv \varphi[\overset{e}{/}_{y}])$

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• Certificate translators for constant propagation, common sub-expression elimination...

- However, representing the result of the analysis as assertions is only possible for analyses that focus on *state properties*
- Several program analyses focus on *execution traces*, e.g. dead variable elimination. We have developed ad-hoc techniques for those.

A (1) > A (1) > A

- Certificate translators for constant propagation, common sub-expression elimination...
- However, representing the result of the analysis as assertions is only possible for analyses that focus on *state properties*
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A (1) > A (1) > A

- Certificate translators for constant propagation, common sub-expression elimination...
- However, representing the result of the analysis as assertions is only possible for analyses that focus on *state properties*
- Several program analyses focus on *execution traces*, e.g. dead variable elimination. We have developed ad-hoc techniques for those.

Prototype

- Source language: imperative language with functions and arrays
- Target language: RTL with functions and arrays
- Compiler: performs common optimizations
- Verification condition generator: interfaced with Coq
- Certificates
 - Size of certificates does not seem to explode, provided one does local normalization of certificates
 - Type checking modulo selected isomorphisms of types could limit certificate growth
- Abstract framework to prove the existence and correctness of certicate translators
- More expressive languages, more complete compilation chains

Concluding remarks

Marktoberdorf, August 2007 Compilation of certificates

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Contents

Two verification methods for bytecode and their relation to verification methods for source code

- Type system for information flow based confidentiality policies
- Verification condition generator for logical specifications

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Two verification methods for bytecode and their relation to verification methods for source code

- Type system for information flow based confidentiality policies
- Verification condition generator for logical specifications



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Two verification methods for bytecode and their relation to verification methods for source code

- Type system for information flow based confidentiality policies
- Verification condition generator for logical specifications



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Deployment of secure mobile code can benefit from:

- advanced verification mechanisms at bytecode level
- methods to "compile" evidence from producer to consumer
- machine checked proofs of verification mechanisms on consumer side (use reflection)

Many challenges ahead e.g.:

- proof carrying code in distributed setting (result certification)
- combination of language-based and cryptographic-based security



http://mobius.inria.fr