

Proofs with Feasible Computational Content

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Why extract computational content from proofs?

- ▶ Proofs are machine checkable \Rightarrow no logical errors.
- ▶ Program on the proof level \Rightarrow maintenance becomes easier.
Possibility of **program development by proof transformation** (Goad 1980).
- ▶ Discover unexpected content:
 - ▶ Berger 1993: Tait's proof of the existence of normal forms for the typed λ -calculus \Rightarrow "normalization by evaluation".
 - ▶ Content in weak (or "classical") existence proofs, of

$$\tilde{\exists}_x A := \neg \forall_x \neg A,$$

via proof interpretations: (refined) A -translation or Gödel's Dialectica interpretation.

Proof and computation

- ▶ \rightarrow, \forall , decidable prime formulas: **negative** arithmetic A^ω .
- ▶ Computational content (Brouwer, Heyting, Kolmogorov):
by inductively defined predicates only. Examples: $\exists_x A, Acc_{\neg}$.
- ▶ Induction \sim (structural) recursion.
- ▶ Curry-Howard correspondence: formula \sim type.
- ▶ Higher types necessary (nested \rightarrow, \forall).

Base types

U	$:= \mu_{\alpha}\alpha,$
B	$:= \mu_{\alpha}(\alpha, \alpha),$
N	$:= \mu_{\alpha}(\alpha, \alpha \rightarrow \alpha),$
L (ρ)	$:= \mu_{\alpha}(\alpha, \rho \rightarrow \alpha \rightarrow \alpha),$
$\rho \wedge \sigma$	$:= \mu_{\alpha}(\rho \rightarrow \sigma \rightarrow \alpha),$
$\rho + \sigma$	$:= \mu_{\alpha}(\rho \rightarrow \alpha, \sigma \rightarrow \alpha),$
(tree, tlist)	$:= \mu_{\alpha, \beta}(\mathbf{N} \rightarrow \alpha, \beta, \beta \rightarrow \alpha, \alpha \rightarrow \beta \rightarrow \beta),$
bin	$:= \mu_{\alpha}(\alpha, \alpha \rightarrow \alpha \rightarrow \alpha),$
\mathcal{O}	$:= \mu_{\alpha}(\alpha, \alpha \rightarrow \alpha, (\mathbf{N} \rightarrow \alpha) \rightarrow \alpha),$
\mathcal{T}_0	$:= \mathbf{N},$
\mathcal{T}_{n+1}	$:= \mu_{\alpha}(\alpha, (\mathcal{T}_n \rightarrow \alpha) \rightarrow \alpha).$

Types

Definition

$$\rho, \sigma, \tau ::= \mu \mid \rho \rightarrow \sigma.$$

A type is **finitary** if it is a base type

- ▶ with all its “parameter types” finitary, and
- ▶ all its “constructor types” without “functional” recursive argument types.

In the examples above **U**, **B**, **N**, tree, tlist and bin are all finitary, but \mathcal{O} and \mathcal{T}_{n+1} are not. $\mathbf{L}(\rho)$ and $\rho \wedge \sigma$ are finitary if their parameter types ρ, σ are.

Recursion operators

$$\text{tt}^{\mathbf{B}} := C_1^{\mathbf{B}}, \quad \text{ff}^{\mathbf{B}} := C_2^{\mathbf{B}},$$

$$\mathcal{R}_{\mathbf{B}}^{\tau} : \mathbf{B} \rightarrow \tau \rightarrow \tau \rightarrow \tau,$$

$$0^{\mathbf{N}} := C_1^{\mathbf{N}}, \quad S^{\mathbf{N} \rightarrow \mathbf{N}} := C_2^{\mathbf{N}},$$

$$\mathcal{R}_{\mathbf{N}}^{\tau} : \mathbf{N} \rightarrow \tau \rightarrow (\mathbf{N} \rightarrow \tau \rightarrow \tau) \rightarrow \tau,$$

$$\text{nil}^{\mathbf{L}(\rho)} := C_1^{\mathbf{L}(\rho)}, \quad \text{cons}^{\rho \rightarrow \mathbf{L}(\rho) \rightarrow \mathbf{L}(\rho)} := C_2^{\mathbf{L}(\rho)},$$

$$\mathcal{R}_{\mathbf{L}(\rho)}^{\tau} : \mathbf{L}(\rho) \rightarrow \tau \rightarrow (\rho \rightarrow \mathbf{L}(\rho) \rightarrow \tau \rightarrow \tau) \rightarrow \tau,$$

$$(\wedge_{\rho\sigma}^+)^{\rho \rightarrow \sigma \rightarrow \rho \wedge \sigma} := C_1^{\rho \wedge \sigma},$$

$$\mathcal{R}_{\rho \wedge \sigma}^{\tau} : \rho \wedge \sigma \rightarrow (\rho \rightarrow \sigma \rightarrow \tau) \rightarrow \tau.$$

We write $x :: l$ for $\text{cons } x \ l$, and $\langle y, z \rangle$ for $\wedge^+ yz$.

Terms and formulas

We work with **typed variables** x^ρ, y^ρ, \dots

Definition (Terms)

$$r, s, t ::= x^\rho \mid C \mid (\lambda_{x^\rho} r^\sigma)^{\rho \rightarrow \sigma} \mid (r^{\rho \rightarrow \sigma} s^\rho)^\sigma.$$

Definition (Formulas)

$$A, B, C ::= \text{atom}(r^{\mathbf{B}}) \mid A \rightarrow B \mid \forall_{x^\rho} A.$$

atom is a predicate constant lifting a boolean term into a formula.
Hence $\text{atom}(r^{\mathbf{B}})$ means “ r is true”.

Examples

Projections:

$$t0 := \mathcal{R}_{\rho \wedge \sigma}^{\rho} t^{\rho \wedge \sigma}(\lambda_{x^{\rho}, y^{\sigma}} x^{\rho}), \quad t1 := \mathcal{R}_{\rho \wedge \sigma}^{\rho} t^{\rho \wedge \sigma}(\lambda_{x^{\rho}, y^{\sigma}} y^{\sigma}).$$

The **append**-function $:+$: for lists is defined recursively by

$$\begin{aligned} \text{nil} :+ l_2 &:= l_2, \\ (x :: l_1) :+ l_2 &:= x :: (l_1 :+ l_2). \end{aligned}$$

It can be defined as the term

$$l_1 :+ l_2 := \mathcal{R}_{\mathbf{L}(\alpha)}^{\mathbf{L}(\alpha) \rightarrow \mathbf{L}(\alpha)} l_1(\lambda_{l_2} l_2)(\lambda_{x, l_1, p, l_2} (x :: (p l_2))) l_2.$$

Using the append function $:+$: we can define **list reversal** R by

$$\begin{aligned} R \text{ nil} &:= \text{nil}, \\ R(x :: l) &:= (R l) :+ (x :: \text{nil}). \end{aligned}$$

The corresponding term is

$$R l := \mathcal{R}_{\mathbf{L}(\alpha)}^{\mathbf{L}(\alpha)} l \text{ nil}(\lambda_{x, l, p} (p :+ (x :: \text{nil}))).$$

Induction

$$\text{Ind}_{\rho, A}: \forall \rho (A(\text{tt}) \rightarrow A(\text{ff}) \rightarrow A(\rho^{\mathbf{B}})),$$

$$\text{Ind}_{n, A}: \forall m (A(0) \rightarrow \forall n (A(n) \rightarrow A(Sn)) \rightarrow A(m^{\mathbf{N}})),$$

$$\text{Ind}_{l, A}: \forall l (A(\text{nil}) \rightarrow \forall x, l' (A(l') \rightarrow A(x :: l')) \rightarrow A(l^{\mathbf{L}(\rho)})).$$

We also require the **truth axiom** $\text{Ax}_{\text{tt}}: \text{atom}(\text{tt})$.

Natural deduction: assumptions, \rightarrow -rules

derivation	term
$u : A$	u^A
$\frac{\begin{array}{c} [u : A] \\ M \\ B \end{array}}{A \rightarrow B} \rightarrow^+ u$	$(\lambda_{u^A} M^B)^{A \rightarrow B}$
$\frac{\begin{array}{c} M \\ A \rightarrow B \end{array} \quad \begin{array}{c} N \\ A \end{array}}{B} \rightarrow^-$	$(M^{A \rightarrow B} N^A)^B$

Natural deduction: \forall -rules

derivation	term
$\frac{ M \quad A}{\forall_x A} \forall^+ x \quad (\text{VarC})$	$(\lambda_x M^A)^{\forall_x A} \quad (\text{VarC})$
$\frac{ M \quad \forall_x A(x) \quad r}{A(r)} \forall^-$	$(M^{\forall_x A(x)} r)^{A(r)}$

Negative arithmetic A^ω

\rightarrow, \forall , decidable prime formulas. No inductively defined predicates.

$$F := \text{atom}(\text{ff}),$$

$$\neg A := A \rightarrow F,$$

$$\tilde{\exists}_x A := \neg \forall_x \neg A.$$

Lemma (Stability, or principle of indirect proof)

$\vdash \neg \neg A \rightarrow A$, for every formula A in A^ω .

Proof.

Induction on A . For the atomic case one needs boolean induction (i.e., case distinction). □

An alternative: falsity as a predicate variable \perp

In A^ω , we have an “arithmetical” falsity $F := \text{atom}(\text{ff})$. However, in some proofs no knowledge about F is required. Then a **predicate variable** \perp instead of F will do, and we can define

$$\tilde{\exists}_x A := \forall_x (A \rightarrow \perp) \rightarrow \perp.$$

Why is this of interest? We then can substitute an arbitrary formula for \perp , for instance, $\exists_x A$ (the “proper” existential quantifier, to be defined below). Then a proof of $\tilde{\exists}_x A$ is turned into a proof of

$$\forall_x (A \rightarrow \exists_x A) \rightarrow \exists_x A.$$

The premise will be provable. Hence we have a proof of $\exists_x A$.

2. Realizability interpretation

- ▶ Study the “computational content” of a proof.
- ▶ This only makes sense after we have added inductively defined predicates to our “negative” \rightarrow, \forall -language of A^ω .
- ▶ The resulting system will be called **arithmetic with inductively defined predicates**, ID^ω .

Example of an inductively defined predicate

Consider the graph of the list reversal function. The **clauses** or **introduction axioms** are

$$\text{Rev}_0^+ : \forall_{v,w}^U (F \rightarrow \text{Rev}(v, w)),$$

$$\text{Rev}_1^+ : \text{Rev}(\text{nil}, \text{nil}),$$

$$\text{Rev}_2^+ : \forall_{v,w}^U \forall_x (\text{Rev}(v, w) \rightarrow \text{Rev}(v :+: x:, x :: w)).$$

The (strengthened) **elimination axiom** says that Rev is the **least** predicate satisfying the clauses:

$$\text{Rev}^- : \forall_{v,w}^U (\forall_{v,w}^U (F \rightarrow P(v, w)) \rightarrow$$

$$P(\text{nil}, \text{nil}) \rightarrow$$

$$\forall_{v,w}^U \forall_x (\text{Rev}(v, w) \rightarrow P(v, w) \rightarrow P(v :+: x:, x :: w)) \rightarrow$$

$$\text{Rev}(v, w) \rightarrow P(v, w)).$$

The intended meaning of an inductively defined predicate I

- ▶ The clauses correspond to **constructors** of an appropriate algebra μ (better: μ_I).
- ▶ We associate to I of arity $\vec{\rho}$ a new predicate I^r , of arity $(\mu, \vec{\rho})$, where the first argument r of type μ represents a **generation tree**, witnessing how the other arguments \vec{r} were put into I .
- ▶ This object r of type μ is called a **realizer** of the prime formula $I(\vec{r})$.

Example (continued)

Recall the clauses for the graph of the list reversal function

$$\text{Rev}_0^+ : \forall_{v,w}^U (F \rightarrow \text{Rev}(v, w)),$$

$$\text{Rev}_1^+ : \text{Rev}(\text{nil}, \text{nil}),$$

$$\text{Rev}_2^+ : \forall_{v,w}^U \forall_x (\text{Rev}(v, w) \rightarrow \text{Rev}(v :+ : x :, x :: w)).$$

The algebra μ_{Rev} is generated by

- ▶ two constants for the first two clauses, and
- ▶ a constructor of type $\mathbf{N} \rightarrow \mu_{\text{Rev}} \rightarrow \mu_{\text{Rev}}$ for the final clause.

Uniformity

- ▶ We want to select relevant parts of the computational content of a proof.
- ▶ This will be possible if some uniformities hold; we express this fact by using a **uniform** variant \forall^U of \forall (as done by Berger 2005) and \rightarrow^U of \rightarrow .
- ▶ Both are governed by the same rules as the non-uniform ones. However, we will put some uniformity conditions on a proof to ensure that the extracted computational content is correct.

Example: existential quantifier

The (proper) existential quantifier is introduced as an inductively defined predicate with parameters. We have four variants, whose introduction axioms are

$$\begin{aligned}\exists^+ &: \quad \forall_x (A \rightarrow \exists_x A), \\ (\exists^L)^+ &: \quad \forall_x (A \rightarrow^U \exists_x^L A), \\ (\exists^R)^+ &: \quad \forall_x^U (A \rightarrow \exists_x^R A), \\ (\exists^U)^+ &: \quad \forall_x^U (A \rightarrow^U \exists_x^U A).\end{aligned}$$

Here $\exists_x A$ abbreviates $\text{Ex}(\rho, \{x^\rho \mid A\})$ (similar for the others).

Example: existential quantifier (continued)

The elimination axioms are (with $x \notin FV(C)$)

$$\exists^-: \quad \exists_x A \rightarrow \forall_x (A \rightarrow C) \rightarrow C,$$

$$(\exists^L)^-: \quad \exists_x^L A \rightarrow \forall_x (A \rightarrow^U C) \rightarrow C,$$

$$(\exists^R)^-: \quad \exists_x^R A \rightarrow \forall_x^U (A \rightarrow C) \rightarrow C,$$

$$(\exists^U)^-: \quad \exists_x^U A \rightarrow \forall_x^U (A \rightarrow^U C) \rightarrow C.$$

Example: Leibniz equality

The introduction axioms are

$$\text{Eq}_0^+ : \forall_{n,m}^U (F \rightarrow \text{Eq}(n, m)), \quad \text{Eq}_1^+ : \forall_n^U \text{Eq}(n, n),$$

and the elimination axiom is

$$\text{Eq}^- : \forall_{n,m}^U (\text{Eq}(n, m) \rightarrow \forall_n^U P(n, n) \rightarrow P(n, m)).$$

One can prove symmetry, transitivity and **compatibility** of Eq:

Lemma (CompatEq)

$$\forall_{n,m}^U (\text{Eq}(n, m) \rightarrow Q(n) \rightarrow Q(m)).$$

Proof.

Use Eq^- , with $P(n, m) := Q(n) \rightarrow Q(m)$. □

Example: falsity

This example is somewhat extreme: the only introduction axiom is

$$\perp_{\text{id}}^+ : F \rightarrow \perp_{\text{id}}$$

and the elimination axiom

$$\perp_{\text{id}}^- : (F \rightarrow C) \rightarrow \perp_{\text{id}} \rightarrow C.$$

Example: pointwise equality $=_{\rho}$

For every arrow type $\rho \rightarrow \sigma$ we have the introduction axiom

$$\forall_{x_1, x_2}^U (\forall_y (x_1 y =_{\sigma} x_2 y) \rightarrow x_1 =_{\rho \rightarrow \sigma} x_2).$$

Introduction axioms for $=_{\mu}$: Example with $\mathbf{T} := \mathcal{T}_1$:

$$\forall_{x_1, x_2}^U (F \rightarrow x_1 =_{\mathbf{T}} x_2),$$

$$0 =_{\mathbf{T}} 0,$$

$$\forall_{f_1, f_2}^U (\forall_n (f_1 n =_{\mathbf{T}} f_2 n) \rightarrow \text{Sup} f_1 =_{\mathbf{T}} \text{Sup} f_2).$$

The elimination axiom is

$$\begin{aligned} =_{\mathbf{T}}^- : \forall_{x_1, x_2}^U (x_1 =_{\mathbf{T}} x_2 \rightarrow P(0, 0) \rightarrow \\ \forall_{f_1, f_2}^U (\forall_n (f_1 n =_{\mathbf{T}} f_2 n) \rightarrow \forall_n P(f_1 n, f_2 n) \rightarrow \\ P(\text{Sup} f_1, \text{Sup} f_2)) \rightarrow \\ P(x_1, x_2)). \end{aligned}$$

Example: pointwise equality (continued)

One can prove **reflexivity** of $=_{\rho}$, using meta-induction on ρ :

Lemma (RefIPtEq)

$$\forall n (n =_{\rho} n).$$

A consequence is that Leibniz equality implies pointwise equality:

Lemma (EqToPtEq)

$$\forall n_1, n_2 (\text{Eq}(n_1, n_2) \rightarrow n_1 =_{\rho} n_2).$$

Proof.

Use `CompatEq` and `RefIPtEq`. □

Axioms

We express **extensionality** of our intended model by stipulating that pointwise equality implies Leibniz equality:

$$\text{PtEqToEq}: \forall_{n_1, n_2} (n_1 =_{\rho} n_2 \rightarrow \text{Eq}(n_1, n_2)).$$

This implies

Lemma (CompatPtEqFct)

$$\forall_f \forall_{n_1, n_2}^U (n_1 =_{\rho} n_2 \rightarrow fn_1 =_{\sigma} fn_2).$$

Proof.

We obtain $\text{Eq}(n_1, n_2)$ by PtEqToEq. By ReflPtEq we have $fn_1 =_{\sigma} fn_1$, hence $fn_1 =_{\sigma} fn_2$ by CompatEq. □

We write **E-ID^ω** when the extensionality axioms are present.

In E-ID^ω we can prove properties of the constructors of base types: they are **injective**, and have **disjoint ranges**.

Axioms (continued)

Let $\check{\exists}$ denote any of $\exists, \exists^R, \exists^L, \exists^U$. When $\check{\exists}$ appears more than once, it is understood that it denotes the same quantifier each time.

The **axiom of choice** (AC) is the scheme

$$\forall_{x\rho} \check{\exists}_{y\sigma} A(x, y) \rightarrow \check{\exists}_{f\rho \rightarrow \sigma} \forall_{x\rho} A(x, f(x)).$$

Independence axioms express the intended meaning of uniformities.

The **independence of premise** axiom (IP) is

$$(A \rightarrow^U \check{\exists}_x B) \rightarrow \check{\exists}_x (A \rightarrow^U B) \quad (x \notin \text{FV}(A)).$$

Similarly we have an **independence of quantifier** axiom (IQ) axiom

$$\forall_x^U \check{\exists}_y A \rightarrow \check{\exists}_y \forall_x^U A.$$

3. Computational content

We define simultaneously

- ▶ the **type** $\tau(A)$ of a formula A ;
- ▶ when a formula is **computationally relevant**;
- ▶ the formula z **realizes** A , written $z \mathbf{r} A$, for a variable z of type $\tau(A)$;
- ▶ when a formula is **negative**;
- ▶ when an inductively defined predicate requires **witnesses**;
- ▶ for an inductively defined I requiring witnesses, its base type μ_I ;
- ▶ for an inductively defined predicate I of arity $\vec{\rho}$ requiring witnesses, a **witnessing** predicate I^r of arity $(\mu_I, \vec{\rho})$.

The type of a formula

- ▶ Every formula A possibly containing inductively defined predicates can be seen as a **computational problem**. We define $\tau(A)$ as the type of a potential realizer of A , i.e., the type of the term (or **program**) to be extracted from a proof of A .
- ▶ More precisely, we assign to A an object $\tau(A)$ (a type or the “nulltype” symbol ε). In case $\tau(A) = \varepsilon$ proofs of A have no computational content.

$$\tau(\text{atom}(r)) := \varepsilon, \quad \tau(I(\vec{r})) := \begin{cases} \varepsilon & \text{if } I \text{ does not require witnesses} \\ \mu_I & \text{otherwise,} \end{cases}$$

$$\tau(A \rightarrow B) := (\tau(A) \rightarrow \tau(B)), \quad \tau(\forall_{x^\rho} A) := (\rho \rightarrow \tau(A)),$$

$$\tau(A \rightarrow^U B) := \tau(B), \quad \tau(\forall_{x^\rho}^U A) := \tau(A)$$

with the convention

$$(\rho \rightarrow \varepsilon) := \varepsilon, \quad (\varepsilon \rightarrow \sigma) := \sigma, \quad (\varepsilon \rightarrow \varepsilon) := \varepsilon.$$

Realizability

Let A be a formula and z either a variable of type $\tau(A)$ if it is a type, or the nullterm symbol ε if $\tau(A) = \varepsilon$. We define the formula $z \mathbf{r} A$, to be read **z realizes A** . The definition uses I^r .

$$z \mathbf{r} \text{atom}(s) \quad := \text{atom}(s),$$

$$z \mathbf{r} I(\vec{s}) \quad := \begin{cases} I(\vec{s}) & \text{if } I \text{ does not require witnesses} \\ I^r(z, \vec{s}) & \text{if not,} \end{cases}$$

$$z \mathbf{r} (A \rightarrow B) \quad := \forall_x (x \mathbf{r} A \rightarrow zx \mathbf{r} B),$$

$$z \mathbf{r} (\forall_x A) \quad := \forall_x zx \mathbf{r} A,$$

$$z \mathbf{r} (A \rightarrow^U B) \quad := (A \rightarrow z \mathbf{r} B),$$

$$z \mathbf{r} (\forall_x^U A) \quad := \forall_x z \mathbf{r} A$$

with the convention $\varepsilon x := \varepsilon$, $z\varepsilon := z$, $\varepsilon\varepsilon := \varepsilon$.

Formulas without inductively defined predicates requiring witnesses are called **negative**. Example: $z \mathbf{r} A$. For A negative, $(\varepsilon \mathbf{r} A) = A$.

Witnesses

Definition (Uniform one-clause inductive definition)

- ▶ there is at most one clause apart from an eq-clause, and
- ▶ this clause is uniform, i.e., contains no \forall but \forall^U only, and its premises are either negative or followed by \rightarrow^U .

Examples: \exists^U , \perp_{id} , Eq.

An inductively defined predicate **requires witnesses** if it is not one of those, and not one of the predicates I^r introduced below.

For an inductively defined predicate I requiring witnesses, we define μ_I to be the corresponding component of the types $\vec{\mu} = \mu_{\vec{\alpha}\vec{\kappa}}$ generated from “constructor types” $\kappa_j := \tau(K_j)$ for all “constructor formulas” K_0, \dots, K_{k-1} from $\vec{I} = \mu_{\vec{X}}(K_0, \dots, K_{k-1})$.

Extracted terms and uniform derivations

We define the extracted term of a derivation, and (using this concept) the notion of a uniform proof, which gives a special treatment to the uniform universal quantifier \forall^U and uniform implication \rightarrow^U .

More precisely, for a proof M in $ID^\omega + AC + IP + IQ$, we simultaneously define

- ▶ its **extracted term** $\llbracket M \rrbracket$, of type $\tau(A)$, and
- ▶ when M is **uniform**.

Extracted terms and uniform proofs

For derivations M^A where $\tau(A) = \varepsilon$ (i.e., A is a Harrop formula) let $\llbracket M \rrbracket := \varepsilon$ (the **nullterm** symbol); every such M is **uniform**. Now assume that M derives a formula A with $\tau(A) \neq \varepsilon$. Then

$$\begin{aligned}\llbracket u^A \rrbracket &:= x_u^{\tau(A)} \quad (x_u^{\tau(A)} \text{ uniquely associated with } u^A), \\ \llbracket (\lambda_{u^A} M)^{A \rightarrow B} \rrbracket &:= \lambda_{x_u^{\tau(A)}} \llbracket M \rrbracket, \\ \llbracket M^{A \rightarrow B} N \rrbracket &:= \llbracket M \rrbracket \llbracket N \rrbracket, \\ \llbracket (\lambda_{x^\rho} M)^{\forall x^A} \rrbracket &:= \lambda_{x^\rho} \llbracket M \rrbracket, \\ \llbracket M^{\forall x^A} r \rrbracket &:= \llbracket M \rrbracket r, \\ \llbracket (\lambda_{u^A}^U M)^{A \rightarrow^U B} \rrbracket &:= \llbracket M^{A \rightarrow^U B} N \rrbracket := \llbracket (\lambda_{x^\rho}^U M)^{\forall x^A} \rrbracket := \llbracket M^{\forall x^A} r \rrbracket := \llbracket M \rrbracket.\end{aligned}$$

In all these cases uniformity is preserved, except possibly in those involving λ^U :

Extracted terms and uniform proofs (continued)

Consider

$$\frac{[u: A] \quad | M}{A \rightarrow^U B} (\rightarrow^U)^+ u \quad \text{or as term} \quad (\lambda_{u^A}^U M)^{A \rightarrow^U B}.$$

$(\lambda_{u^A}^U M)^{A \rightarrow^U B}$ is **uniform** if M is and $x_u \notin \text{FV}(\llbracket M \rrbracket)$. Similarly:
Consider

$$\frac{| M}{\forall_x^U A} (\forall^U)^+ x \quad \text{or as term} \quad (\lambda_x^U M)^{\forall_x^U A} \quad (\text{VarC}).$$

$(\lambda_x^U M)^{\forall_x^U A}$ is **uniform** if M is and $x \notin \text{FV}(\llbracket M \rrbracket)$.

Extracted terms for axioms

The extracted term of an induction axiom is defined to be a recursion operator. For example, in case of an induction scheme

$$\text{Ind}_{n,A} : \forall_m (A(0) \rightarrow \forall_n (A(n) \rightarrow A(Sn)) \rightarrow A(m^{\mathbf{N}}))$$

we have

$$\llbracket \text{Ind}_{n,A} \rrbracket := \mathcal{R}_{\mathbf{N}}^{\tau} : \mathbf{N} \rightarrow \tau \rightarrow (\mathbf{N} \rightarrow \tau \rightarrow \tau) \rightarrow \tau \quad (\tau := \tau(A) \neq \varepsilon).$$

For the introduction/elimination axioms of an inductively defined predicate I we define

$$\llbracket (I_j)^+ \rrbracket := C, \quad \llbracket I_j^- \rrbracket := \mathcal{R}_j,$$

and similar for the introduction and elimination axioms for I^r .
As extracted terms of (AC), (IP) and (IQ) we take identities of the appropriate types.

Uniform derivations

Lemma

There are purely logical uniform derivations of

- ▶ $A \rightarrow B$ from $A \rightarrow^U B$;
- ▶ $A \rightarrow^U B$ from $A \rightarrow B$, provided $\tau(A) = \varepsilon$ or $\tau(B) = \varepsilon$;
- ▶ $\forall_x A$ from $\forall_x^U A$;
- ▶ $\forall_x^U A$ from $\forall_x A$, provided $\tau(A) = \varepsilon$.

In formulas involving \rightarrow^U and \forall^U we can replace a subformula by an equivalent one:

Lemma

There are purely logical uniform derivations of

- ▶ $(A \rightarrow^U B) \rightarrow (B \rightarrow B') \rightarrow A \rightarrow^U B'$;
- ▶ $(A' \rightarrow A) \rightarrow^U (A \rightarrow^U B) \rightarrow A' \rightarrow^U B$;
- ▶ $\forall_x^U A \rightarrow (A \rightarrow A') \rightarrow \forall_x^U A'$.

Characterization

When a formula A and its modified realizability interpretation $\exists_x x \mathbf{r} A$ are equivalent?

Theorem (Characterization)

In $ID^\omega + AC + IP + IQ$ we can derive

$$A \leftrightarrow \exists_x x \mathbf{r} A.$$

Proof.

Induction on A .



Soundness

Every theorem in $E\text{-ID}^\omega + AC + IP + IQ + Ax_\varepsilon$ has a realizer.
Here (Ax_ε) is an arbitrary set of Harrop formulas (i.e., $\tau(A) = \varepsilon$)
viewed as axioms.

Theorem (Soundness)

We work in $ID^\omega + AC + IP + IQ$. Let M be a derivation of A from assumptions $u_i : C_i$ ($i < n$). Then we can find a derivation $\sigma(M)$ of $\llbracket M \rrbracket \mathbf{r} A$ from assumptions $\bar{u}_i : x_{u_i} \mathbf{r} C_i$ for a non-uniform u_i (i.e., $x_{u_i} \in FV(\llbracket M \rrbracket)$), and $\bar{u}_i : C_i$ for the other ones.

Proof.

Induction on A . □

Example: list reversal, constructive proof

View `Rev` as a variable for a binary boolean-valued function. It is axiomatized by

```
RevNil:    Rev(Nil nat)(Nil nat)
```

```
RevCons:  all v,w,x(Rev v w -> Rev(v::x:)(x::w))
```

Every non-empty list can be written in the form $v :: y$.

```
; "ListInitLastNat"
```

```
(set-goal (pf "all u,x ex v,y (x::u)=v::y:"))
```

Proof of $\forall v \exists w \text{Rev}(v, w)$, by induction on $\text{lh}(v)$.

Step: since the list is non-empty, it can be written as $v :: y$.
 v has a smaller length. Hence the IH yields its reversal w . Take
 $y :: w$.

Example: list reversal, constructive proof (continued)

```
; "ListRevNatEx"  
(set-goal  
  (pf "allnc Rev(  
    Rev(nil nat)(nil nat) ->  
    all v,w,x(Rev v w -> Rev(v::x::w)) ->  
    all n,v(n=Lh v -> ex w Rev v w))"))
```

Extracted term:

```
[x0]  
(Rec nat=>list nat=>list nat)x0([v2](nil nat))  
([x2,f3,v4]  
  [if v4  
    (nil nat)  
    ([x5,v6][let p7 (cListInitLastNat v6 x5)  
              (right p7::f3 left p7)])])])
```

Example: list reversal, constructive proof (continued)

More readable form: Recursion equations for $g := \text{cListInitLastNat}$:

$$\begin{aligned}g(\text{nil}, z) &= (\text{nil}, z), \\g(x :: u, z) &= \mathbf{let} (v, y) = g(u, x) \mathbf{in} (z :: v, y).\end{aligned}$$

Recursion equations for $h := \text{cListRevNatEx}$:

$$\begin{aligned}h(0, u) &= \text{nil}, \\h(n + 1, \text{nil}) &= \text{nil}, \\h(n + 1, x :: u) &= \mathbf{let} (v, y) = g(u, x) \mathbf{in} y :: h(n, v).\end{aligned}$$

We have extracted a quadratic algorithm.

```
(animate "ListInitLastNat")
(animate "Id")
(pp (nt (mk-term-in-app-form
        net (pt "4") (pt "1::2::3::4:"))))
; 4::3::2::1:
```


Example: list reversal, classical proof

From the “false” assumption $\forall_w(\text{Rev}(v_0, w) \rightarrow \perp)$ we show that all initial segments of v_0 are non-revertible, by list induction:

```
; "InitSegNonRevStepU"
(set-goal
  (pf "all Rev(
    all v,w,x(Rev v w -> Rev(v::x:)(x::w)) ->
    all v0,x,u(
      allnc v(v::u=v0 -> all w(Rev v w -> bot)) ->
      allnc v(v::(x::u)=v0 -> all w(Rev v w -> bot))))"))

(pp (proof-to-extracted-term
    (theorem-name-to-proof "InitSegNonRevStepU")))
; [Rev,v0,x,u,h992,w]h992(x::w)
```

Note: $\text{h992}(x::w)$ does **not** involve v . Hence $\text{allnc } v$ is correct.

Example: list reversal, classical proof (continued)

```
; "InitSegNonRevU"
(set-goal
  (pf "all Rev(
    all v,w,x(Rev v w -> Rev(v::x:)(x::w)) ->
    all v0(
      all w(Rev v0 w -> bot) ->
      all u allnc v(v::u=v0 -> all w(Rev v w -> bot))))"))

; "RevClassU"
(set-goal
  (pf "all Rev,v(
    Rev(Nil nat)(Nil nat) ->
    all v,w,x(Rev v w -> Rev(v::x:)(x::w)) ->
    excl w Rev v w)"))
```

Example: list reversal, classical proof (continued)

- ▶ Substitute $\exists_w \text{Rev}(v, w)$ for \perp ,
- ▶ insert the trivial proof of $\forall_w (\text{Rev}(v, w) \rightarrow \exists_w \text{Rev}(v, w))$,
- ▶ extract a term from the resulting proof of $\exists_w \text{Rev}(v, w)$ and
- ▶ normalize it, after “animating” `InitSegNonRevU`, and `InitSegNonRevStepU`. Let `net` be the result.

(pp net)

```
; [Rev0,v1]
; (Rec list nat=>list nat=>list nat)v1([v2]v2)
;   ([x2,v3,f4,v5]f4(x2::v5))
; (Nil nat)
```

More readable form: $f(v_1) = g(v_1, \text{nil})$ with

$$g(\text{nil}, v_2) = v_2, \quad g(x :: v_1, v_2) = g(v_1, x :: v_2).$$

We have extracted the usual linear algorithm.

4. Complexity

- ▶ Practically far too high, already for ground type structural (“primitive”) recursion.
- ▶ Bellantoni and Cook (1992) characterized the polynomial time functions by the primitive recursion scheme, separating the variables into two sorts, as proposed by Simmons (1988):
- ▶ **Input** (or **normal**) variables control the length of recursion.
- ▶ **Output** (or **safe**) variables mark positions where substitution is allowed.

Here: extension to higher types.

The fast growing hierarchy $\{F_\alpha\}_{\alpha < \varepsilon_0}$

Grzegorzcyk 1953, Robbin 1965, Löb and Wainer 1970, S. 1971

$$F_\alpha(n) = \begin{cases} n + 1 & \text{if } \alpha = 0 \\ F_{\alpha-1}^{n+1}(n) & \text{if Succ}(\alpha) \\ F_{\alpha(n)}(n) & \text{if Lim}(\alpha) \end{cases}$$

where $F_{\alpha-1}^{n+1}(n)$ is the $n + 1$ -times iterate of $F_{\alpha-1}$ on n .

- ▶ F_ω is the Ackermann function.
- ▶ F_{ε_0} grows faster than all functions definable in arithmetic.

The power of higher types: iteration functionals

Pure types ρ_n : defined by $\rho_0 := \mathbf{N}$ and $\rho_{n+1} := \rho_n \rightarrow \rho_n$.

Let x_n be of pure type ρ_n .

$$F_\alpha x_n \dots x_0 := \begin{cases} x_0 + 1 & \text{if } \alpha = 0 \text{ and } n = 0, \\ x_n^{x_0} x_{n-1} \dots x_0 & \text{if } \alpha = 0 \text{ and } n > 0, \\ F_{\alpha-1}^{x_0} x_n \dots x_0 & \text{if Succ}(\alpha), \\ F_{\alpha(x_0)} x_n \dots x_0 & \text{if Lim}(\alpha). \end{cases}$$

Lemma

$F_\alpha F_\beta = F_{\beta + \omega^\alpha}$. Hence all F_α are definable from F_0 's (= iterators).

A two-sorted variant $\mathbb{T}(\cdot)$ of Gödel's \mathbb{T}

The two-sortedness restriction is lifted to higher types.

We shall work with two forms of arrow types and abstraction terms:

$$\left\{ \begin{array}{l} \mathbf{N} \rightarrow \sigma \\ \lambda_n r \end{array} \right. \quad \text{as well as} \quad \left\{ \begin{array}{l} \rho \multimap \sigma \\ \lambda_z r \end{array} \right.$$

and a corresponding syntactic distinction between **input** $n^{\mathbf{N}}$ and **output** $a^{\mathbf{N}}, z^{\rho}$ (typed) variables. Intuition:

- ▶ A function of type $\mathbf{N} \rightarrow \sigma$ may recurse on its argument, but
- ▶ a function of type $\mathbf{N} \multimap \sigma$ may **not**.

The **types** are

$$\rho, \sigma, \tau ::= \mathbf{N} \mid \mathbf{N} \rightarrow \rho \mid \rho \multimap \sigma.$$

The \rightarrow -free types are called **safe**.

Constants, terms

The **constants** are $0: \mathbf{N}$, $S: \mathbf{N} \multimap \mathbf{N}$ and, for safe τ ,

$$\mathcal{C}_\tau: \mathbf{N} \multimap \tau \multimap (\mathbf{N} \multimap \tau) \multimap \tau,$$

$$\mathcal{R}_\tau: \mathbf{N} \rightarrow \tau \multimap (\mathbf{N} \rightarrow \tau \multimap \tau) \multimap \tau.$$

The first argument of \mathcal{R} is the input (recursion) argument. Hence $\mathbf{N} \rightarrow \cdot$.

$\mathbb{T}(\cdot)$ -**terms** (terms for short) are

$$r, s, t ::= x \mid C \mid (\lambda_n r)^{\mathbf{N} \rightarrow \sigma} \mid r^{\mathbf{N} \rightarrow \sigma} s^{\mathbf{N}} \text{ (s input term)} \mid \\ (\lambda_z r)^{\rho \multimap \sigma} \mid r^{\rho \multimap \sigma} s^\rho.$$

s is an **input term** if all its free variables are input variables.

Examples

Addition:

$$a + 0 := a, \quad a + (Sn) := S(a + n).$$

Representing term:

$$t_+ := \lambda_{a,n} \cdot \mathcal{R}_{\mathbf{N}} n a (\lambda_{n,p} \cdot Sp): \mathbf{N} \multimap \mathbf{N} \rightarrow \mathbf{N}.$$

Predecessor P :

$$t_P := \lambda_a \cdot \mathcal{C}_{\mathbf{N}} a 0 (\lambda_b b): \mathbf{N} \multimap \mathbf{N}.$$

Modified subtraction $\dot{\div}$:

$$a \dot{\div} 0 := a, \quad a \dot{\div} (Sn) := P(a \dot{\div} n).$$

Representing term:

$$t_{\dot{\div}} := \lambda_{a,n} \cdot \mathcal{R}_{\mathbf{N}} n a (\lambda_{n,p} \cdot Pp): \mathbf{N} \rightarrow \mathbf{N}.$$

Example: bounded summation, exponential

Let $f(\vec{n}, n) := \sum_{i < n} g(\vec{n}, i)$, i.e.,

$$f(\vec{n}, 0) := 0, \quad f(\vec{n}, Sn) := f(\vec{n}, n) + g(\vec{n}, n).$$

Representing term:

$$t_f := \lambda_{\vec{n}, n}. \mathcal{R}_{\mathbf{N}n0}(\lambda_{n,p}.p + (t_g \vec{n}n)) : \mathbf{N}^{(k+1)} \rightarrow \mathbf{N}$$

Let $B(n, a) := a + 2^n$, i.e.,

$$B(0, a) = a + 1,$$

$$B(n + 1, a) = B(n, B(n, a)).$$

Representing term:

$$t_B := \lambda_n. \mathcal{R}_{\mathbf{N} \rightarrow \mathbf{N}nS}(\lambda_{m,p,a}.(p^{\mathbf{N} \rightarrow \mathbf{N}}(pa))) : \mathbf{N} \rightarrow \mathbf{N} \rightarrow \mathbf{N}$$

Elementary functions are definable in $T(;$)

The class \mathcal{E} of **elementary functions** consists of those number theoretic functions which can be defined from

- ▶ the **initial functions**: constant 0, successor S , projections (onto the i th coordinate), addition $+$, modified subtraction $\dot{-}$, multiplication \cdot and exponentiation 2^x
- ▶ by applications of **composition** and **bounded minimization**.

Bounded minimization

$$f(\vec{n}, m) = \mu_{k < m} (g(\vec{n}, k) = 0)$$

is definable from bounded summation and $\dot{-}$:

$$f(\vec{n}, m) = \sum_{i < m} (1 \dot{-} \sum_{k \leq i} (1 \dot{-} g(\vec{n}, k))).$$

The claim follows from the examples above.

Necessity of the restrictions on the type of \mathcal{R}

Define the **pure safe types** ρ_k , by $\rho_0 := \mathbf{N}$ and $\rho_{k+1} := \rho_k \multimap \rho_k$.
In $\mathsf{T}(\cdot)$ we can define

$$I_n a_k \dots a_0 := a_k^n a_{k-1} \dots a_0,$$

with a_k of type ρ_k . However, a definition $F_0 a_k \dots a_0 := I_{a_0} a_k \dots a_0$ is **not** possible: I_{a_0} is not allowed.

The **value type** is a **safe type**:

$$I_E := \lambda_n. \mathcal{R}_{\mathbf{N} \rightarrow \mathbf{N}} n (\lambda_m m) (\lambda_{n,p,m} (p^{\mathbf{N} \rightarrow \mathbf{N}} (Em))),$$

and $I_E(n, m) = E^n(m)$, a function of superelementary growth.

The **“previous”-variable** is an **output variable**:

$$S := \lambda_n. \mathcal{R}_{\mathbf{N}} n 0 (\lambda_{n,m} (Em))$$

Then $S(n) = E^n(0)$, which is superelementary.

Theorem (Normalization)

Let t be a closed $\mathbb{T}(\cdot)$ -term of type $\mathbf{N} \multimap \dots \mathbf{N} \multimap \mathbf{N}$ ($\multimap \in \{\rightarrow, \multimap\}$). Then t denotes an elementary function.

Proof.

- ▶ Let \vec{x} be new variables such that $t\vec{x}$ is of type \mathbf{N} . The β normal form $\beta\text{-nf}(t\vec{x})$ of $t\vec{x}$ is computed in an amount of time that may be large, but it is only a constant with respect to \vec{n} .
- ▶ By \mathcal{R} Elimination one reduces to an \mathcal{R} -free term $\text{rf}(\beta\text{-nf}(t\vec{x}); \vec{x}; \vec{n})$ in time $F_t(|\vec{n}|)$ with F_t elementary.
- ▶ Since the running time bounds the size of the produced term, $|\text{rf}(\beta\text{-nf}(t\vec{x}); \vec{x}; \vec{n})| \leq F_t(|\vec{n}|)$.
- ▶ A further β -normalization computes $\beta\mathcal{R}\text{-nf}(t\vec{n}) = \beta\text{-nf}(\text{rf}(\beta\text{-nf}(t\vec{x}); \vec{x}; \vec{n}))$ in time elementary in $|\vec{n}|$.
- ▶ Finally in time linear in the result we can remove all occurrences of \mathcal{C} and arrive at a numeral.

A linear two-sorted variant $LT(;)$ of Gödel's T

Work with a **binary** representation of the natural numbers, with two successors $S_0(a) = 2a$ and $S_1(a) = 2a + 1$.

Recall: for $B(n, a) = a + 2^n$ we had the defining term

$$\lambda_n(\mathcal{R}_{\mathbf{N} \rightarrow \mathbf{N}} n S(\lambda_{m,p,a}(p^{\mathbf{N} \rightarrow \mathbf{N}}(pa))))$$

with the higher type variable p for the “previous” value appearing **twice** in the step term. Here:

- ▶ The term definition will now involve a **linearity** constraint.
- ▶ Change type of \mathcal{R} : its (higher type) step argument will be used many times, and hence we need a \rightarrow after it.

Change names: input/output \mapsto **normal/safe** variables.

Feasible computation with higher types: LT(;

We work with two forms of arrow types and abstraction terms:

$$\left\{ \begin{array}{l} \rho \rightarrow \sigma \\ \lambda_{\bar{x}^{\rho}} r \end{array} \right. \quad \text{as well as} \quad \left\{ \begin{array}{l} \rho \multimap \sigma \\ \lambda_{x^{\rho}} r \end{array} \right.$$

and a corresponding syntactic distinction between **normal** and **safe** (typed) variables, \bar{x} and x . Intuition:

- ▶ A function of type $\rho \rightarrow \sigma$
 - ▶ may recurse on its argument (if of ground type), or
 - ▶ use it many times (if of higher type).
- ▶ A function of type $\rho \multimap \sigma$
 - ▶ may not recurse on its argument (if of ground type), or
 - ▶ can use it only once (if of higher type).

Types

The **types** are

$$\rho, \sigma, \tau ::= \mathbf{U} \mid \mathbf{B} \mid \mathbf{L}(\rho) \mid \rho \rightarrow \sigma \mid \rho \multimap \sigma \mid \rho \wedge \sigma,$$

and the **level** of a type is defined by

$$\begin{aligned} l(\mathbf{U}) &:= 0, & l(\rho \rightarrow \sigma) &:= l(\rho \multimap \sigma) := \max\{l(\sigma), 1 + l(\rho)\}, \\ l(\mathbf{B}) &:= 0, & l(\rho \wedge \sigma) &:= \max\{l(\rho), l(\sigma)\}. \\ l(\mathbf{L}(\rho)) &:= l(\rho), \end{aligned}$$

The \rightarrow -free types are called **safe**.

Constants

The **constants** are $\mathbf{u} : \mathbf{U}$, $\mathbf{tt}, \mathbf{ff} : \mathbf{B}$, $\mathbf{nil}_\rho : \mathbf{L}(\rho)$ and, for safe ρ, τ ,

$$\mathbf{::}_\rho : \rho \multimap \mathbf{L}(\rho) \multimap \mathbf{L}(\rho),$$

$$\mathbf{if}_\tau : \mathbf{B} \multimap \tau \multimap \tau \multimap \tau,$$

$$\mathbf{C}_\tau^\rho : \mathbf{L}(\rho) \multimap \tau \multimap (\rho \multimap \mathbf{L}(\rho) \multimap \tau) \multimap \tau,$$

$$\mathbf{R}_\tau^\rho : \mathbf{L}(\rho) \rightarrow \tau \multimap (\rho \rightarrow \mathbf{L}(\rho) \rightarrow \tau \multimap \tau) \rightarrow \tau \quad (\rho \text{ ground}),$$

$$\mathbf{\wedge}_{\rho\sigma}^+ : \rho \multimap \sigma \multimap \rho \wedge \sigma,$$

$$\mathbf{\wedge}_{\rho\sigma\tau}^- : \rho \wedge \sigma \multimap (\rho \multimap \sigma \multimap \tau) \multimap \tau,$$

Terms

LT(;)-**terms** are built from these constants and typed variables \bar{x}^σ (normal variables) and x^σ (safe variables) by introduction and elimination rules for the two type forms $\rho \rightarrow \sigma$ and $\rho \multimap \sigma$, i.e.,

$\bar{x}^\rho \mid x^\rho \mid C^\rho$ (constant) |
 $(\lambda_{\bar{x}^\rho} r^\sigma)^{\rho \rightarrow \sigma} \mid (r^{\rho \rightarrow \sigma} s^\rho)^\sigma$ (s “normal”) |
 $(\lambda_{x^\rho} r^\sigma)^{\rho \multimap \sigma} \mid (r^{\rho \multimap \sigma} s^\rho)^\sigma$ (higher type safe variables in r, s distinct),

where a term s is called **normal** if all its free variables are normal.

Examples

$x \oplus y$ concatenates $|x|$ bits onto y :

$$\begin{aligned} 1 \oplus y &= S_0 y, \\ (S_i x) \oplus y &= S_0(x \oplus y). \end{aligned}$$

The representing term is

$$\bar{x} \oplus y := \lambda_{\bar{x}, y}. \mathcal{R}_{\mathbf{W} \multimap \mathbf{W}} \bar{x} S_0(\lambda_{\bar{z}, \bar{l}, p, y}. S_0(p^{\mathbf{W} \multimap \mathbf{W}} y)) y : \mathbf{W} \rightarrow \mathbf{W} \multimap \mathbf{W}.$$

$x \odot y$ has output length $|x| \cdot |y|$:

$$\begin{aligned} x \odot 1 &= x, \\ x \odot (S_i y) &= x \oplus (x \odot y). \end{aligned}$$

The representing term is

$$\bar{x} \odot \bar{y} := \lambda_{\bar{x}, \bar{y}}. \mathcal{R}_{\mathbf{W} \bar{y}} \bar{x} (\lambda_{\bar{z}, \bar{l}, p}. \bar{x} \oplus p) : \mathbf{W} \rightarrow \mathbf{W} \rightarrow \mathbf{W}.$$

Polytime computable functions are definable in $LT(;;)$

Bellantoni/Cook (1992) characterized the polynomial time computable functions: some initial functions, **safe composition**

$$f(\vec{x}; \vec{y}) := g(r_1(\vec{x};), \dots, r_m(\vec{x};); s_1(\vec{x}; \vec{y}), \dots, s_n(\vec{x}; \vec{y}))$$

and **safe recursion**:

$$\begin{aligned} f(1, \vec{x}; \vec{y}) &:= g(\vec{x}; \vec{y}), \\ f(S_i n, \vec{x}; \vec{y}) &:= h_i(n, \vec{x}; \vec{y}, f(n, \vec{x}; \vec{y})). \end{aligned}$$

Representing term:

$$\begin{aligned} t_f &:= \lambda_{\vec{n}, \vec{x}}. \mathcal{R}_\tau \bar{n}(t_g \vec{x}) s \quad \text{with} \\ s &:= \lambda_{\vec{x}, \vec{1}, p, \vec{y}}. \text{if } \mathbf{w} \rightarrow \mathbf{w} \bar{x} (\lambda_z. t_{h_0} \vec{1} \vec{x} \vec{y} z) (\lambda_z. t_{h_1} \vec{1} \vec{x} \vec{y} z) (p \vec{y}). \end{aligned}$$

Note p is used only once.

Theorem (Normalization)

Let r be a closed $\text{LT}(\cdot; \cdot)$ -term of type $\mathbf{W} \multimap \dots \mathbf{W} \multimap \mathbf{W}$ ($\multimap \in \{\rightarrow, \multimap\}$). Then r denotes a polytime function.

Proof.

- ▶ Let \vec{x} be new variables of types $\vec{\rho}$. The normal form of $t\vec{x}$ is computed in an amount of time that may be large, but it is still only a constant with respect to \vec{n} .
- ▶ $\text{nf}(t\vec{x})$ is “simple” (i.e., no higher type normal variables).
- ▶ By \mathcal{R} Elimination one reduces to an \mathcal{R} -free simple term $\text{rf}(\text{nf}(t\vec{x}); \vec{x}; \vec{n})$ in time $P_t(|\vec{n}|)$, w.r.t. to a **dag model of computation**.
- ▶ Since the running time bounds the size of the produced term, $|\text{rf}(\text{nf}(t\vec{x}); \vec{x}; \vec{n})| \leq P_t(|\vec{n}|)$.
- ▶ By Sharing Normalization one computes $\text{nf}(t\vec{n}) = \text{nf}(\text{rf}(\text{nf}(t\vec{x}); \vec{x}; \vec{n}))$ in time $O(P_t(|\vec{n}|)^2)$.

Future work

Arithmetic with inductively defined predicates: ID^ω .

- ▶ Fine tuning of computational content: \forall^U and \rightarrow^U .
- ▶ Compare different **proof interpretations**: “refined” A-translation and Gödel’s Dialectica interpretation.

- ▶ Solve

$$\frac{\text{Arithmetic}}{\text{Gödel's } T} = \frac{A(;)}{T(;)} = \frac{LA(;)}{LT(;)}.$$

- ▶ Terms: Gödel’s T over (possibly infinitary) base types, with structural and **general** recursion.
- ▶ Standard semantics: Partial continuous functionals. Terms denote computable functionals. Include **formal neighborhoods** (consistent sets in the sense of Scott’s information systems) into the language.