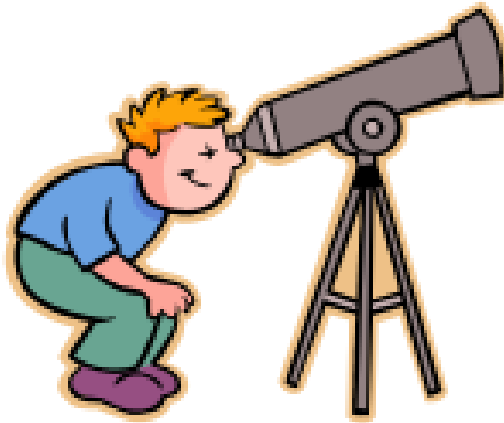


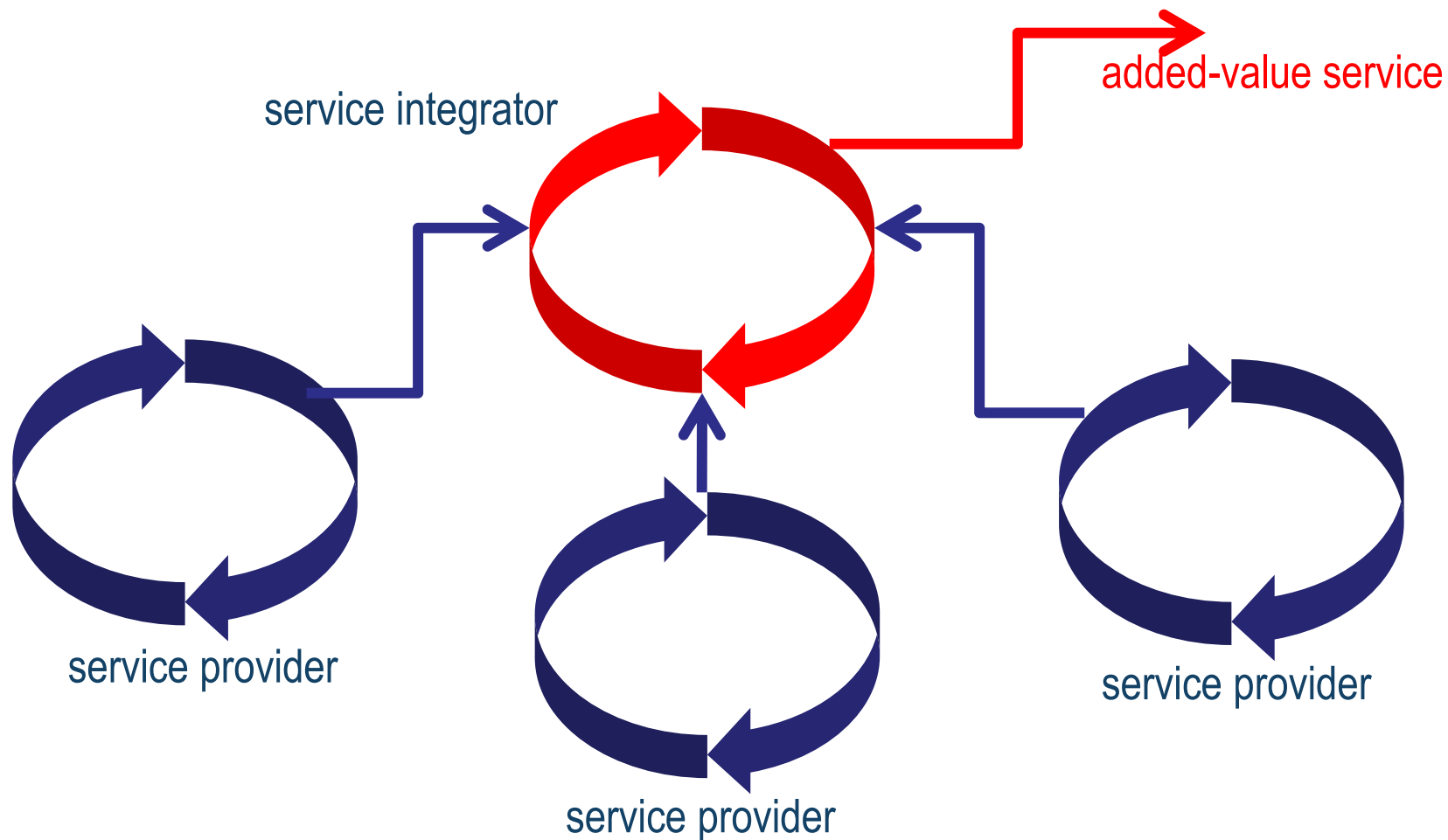


From requirements to specification and (continuous) verification (Part 1 -- SAVVY-WS)



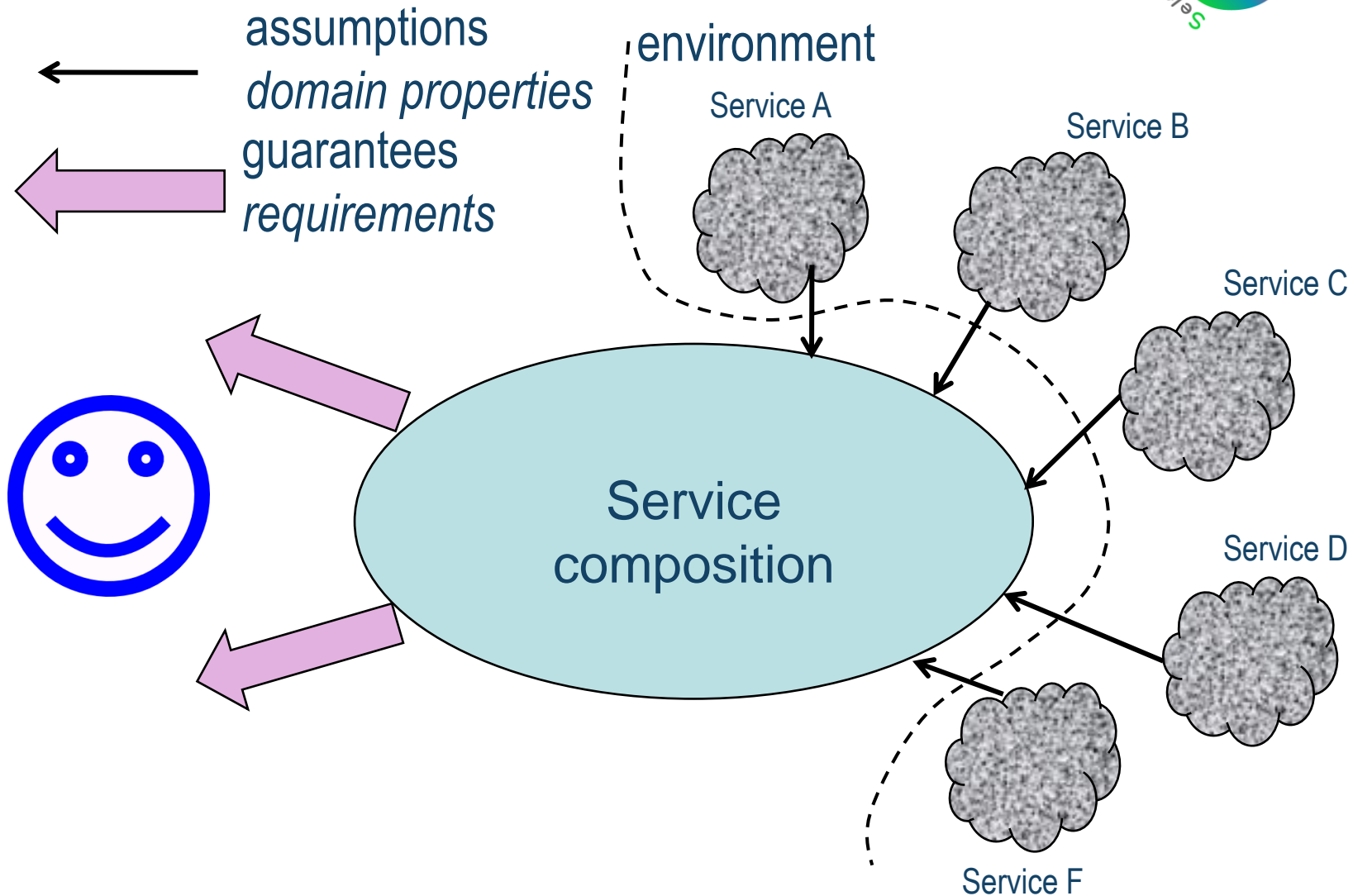


Our setting





Our setting





Open world: the problem

- External services may evolve autonomously
- The assumptions made at design-time may be later invalidated
- What can be done at design-time?
- What needs to be done at run-time?



SAVVY-WS

- **S**ervice **A**nalysis, **V**erification and **V**alidation methodology **Y** for Web Services
 - It supports the development of **verified composite services**, built as BPEL workflows
- Compositions are guaranteed to satisfy certain global correctness properties
- External services are assumed to be known at the level of the interface (**abstract services**) and their assumed behavior is specified as we will describe
 - any **concrete service** that offers a “compatible” interface may be later bound



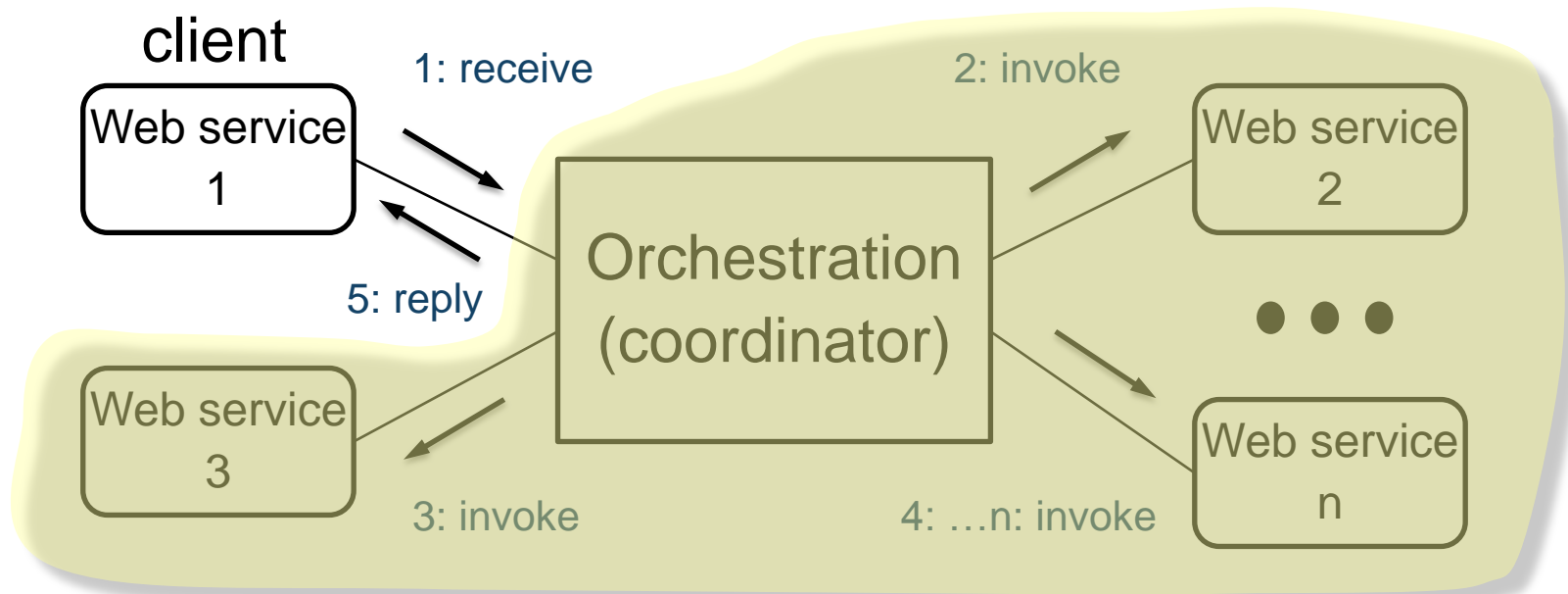
Conceptual approach

- An **assumption-promise** based approach
 - a service integrator **assumes** that the external services used in the composition satisfy their stated specification
 - under this assumption, the system is designed to **promise** a certain service to its clients
- But since the external services may deviate wrt to their stated specification
 - a **monitor** does run-time verification
 - suitable **reactions** may be activated
 - *reactions ignored in this presentation*



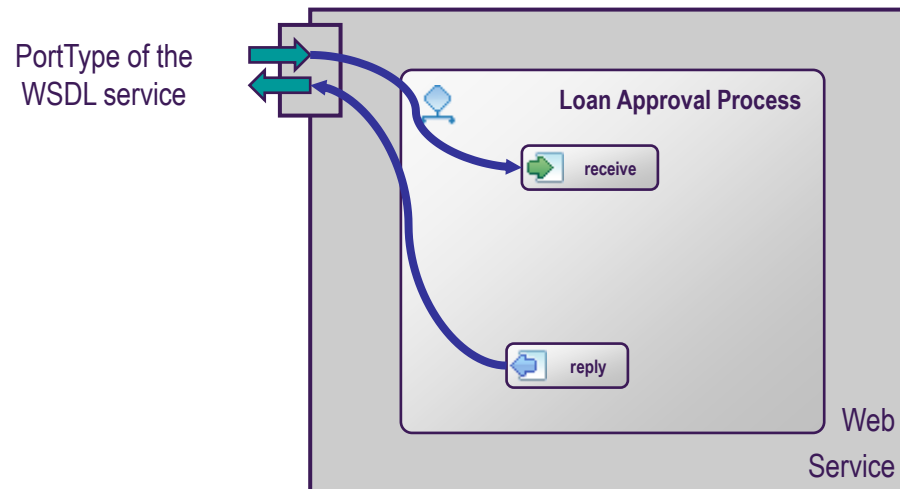
BPEL—Business Process Execution Language

- Supports the definition of Business Processes (BPs) which use external Web Services
- BPs *coordinate* (**orchestrate**) external Web services
- A BPEL BP can be seen in turn as a service



BPEL and WSDL

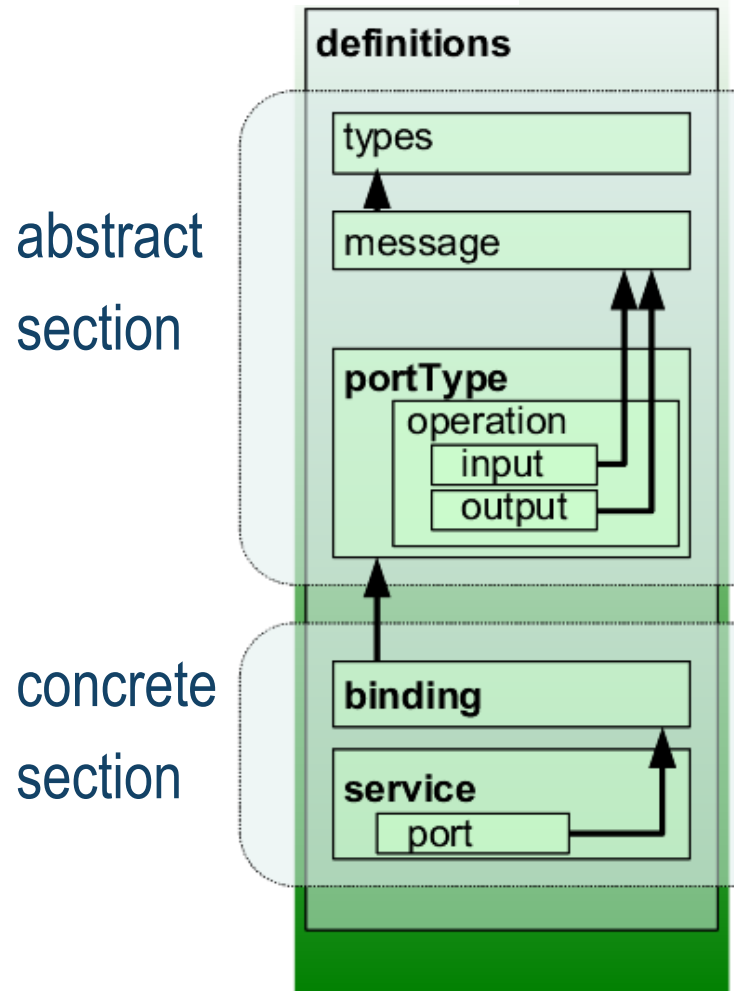
- WSDL Web Service Description Language
 - syntactic description
- BPEL processes are exposed as services through a WSDL interface
 - message exchanges depend on the defined WSDL operations



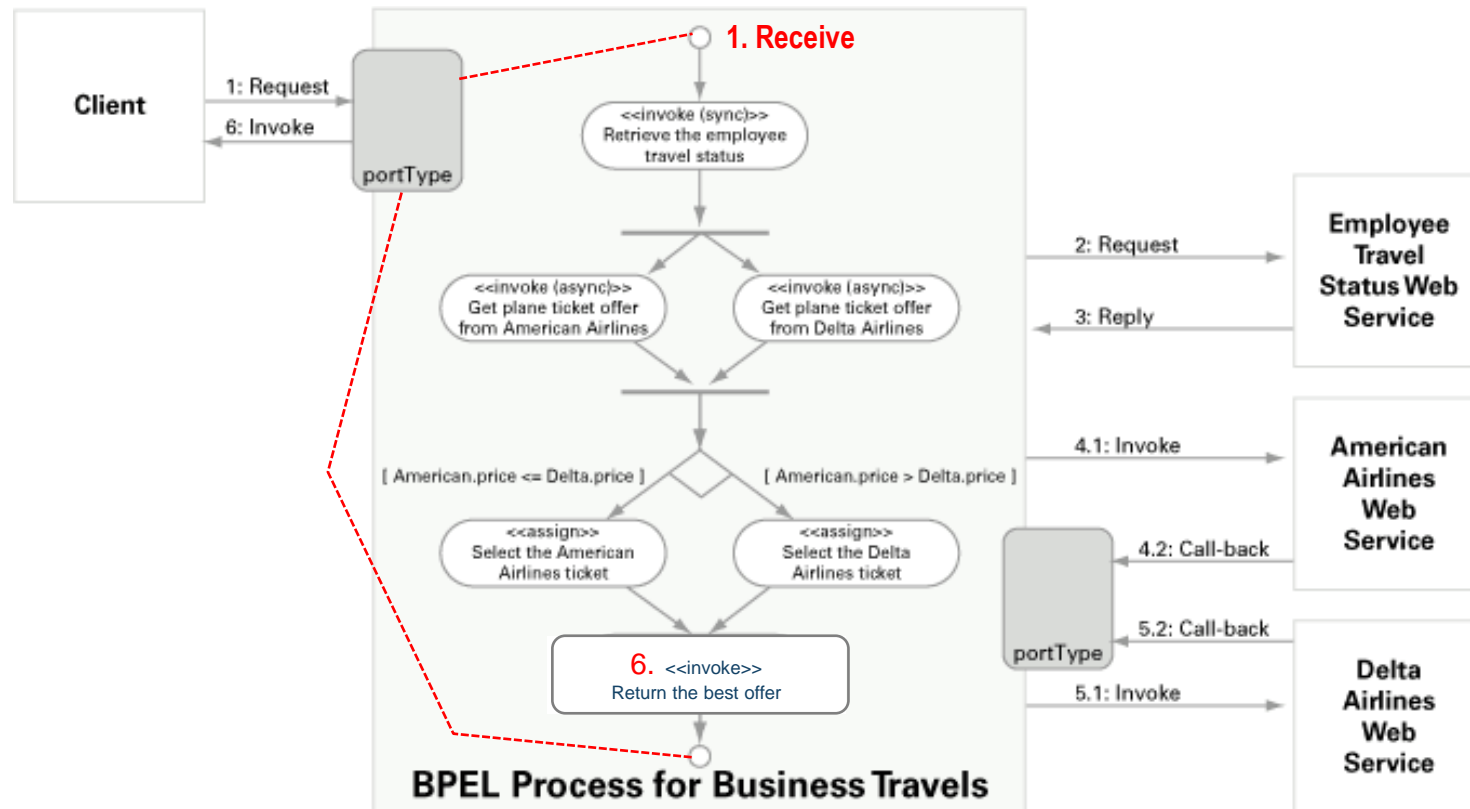


WSDL

- Describes the interface of a service in terms of operations and parameters
- Contains definition of message types
- The description is an XML document



Example: a preview





BPEL Basic Activities

```
<invoke partnerLink="..." portType="..." operation="..."
    inputVariable="..." outputVariable="..."/>
```

<!-- process invokes an operation on a partner: -->

```
<receive partnerLink="..." portType="..." operation="..."
    variable="..." [createInstance="..."]/>
```

<!-- process receives invocation from a partner: -->

```
<reply partnerLink="..." portType="..." operation="..."
    variable="..."/>
```

<!-- process sends reply message in partner invocation: -->

```
<assign>
  <copy>
    <from variable="..."/> <to variable="..."/>
  </copy>+
</assign>
```

<!-- Data assignment between variables -->



More Basic Activities

```
<throw faultName="..." faultVariable="..." />  
  <!-- process signals an internal fault -->
```

```
<terminate />  
  <!-- terminates the process execution -->
```

```
<wait (for="..." | until="...") />  
  <!-- process execution is delayed for a certain period of time or until a  
  certain deadline is reached -->
```

```
<empty />  
  <!-- Do nothing; a convenience element -->
```

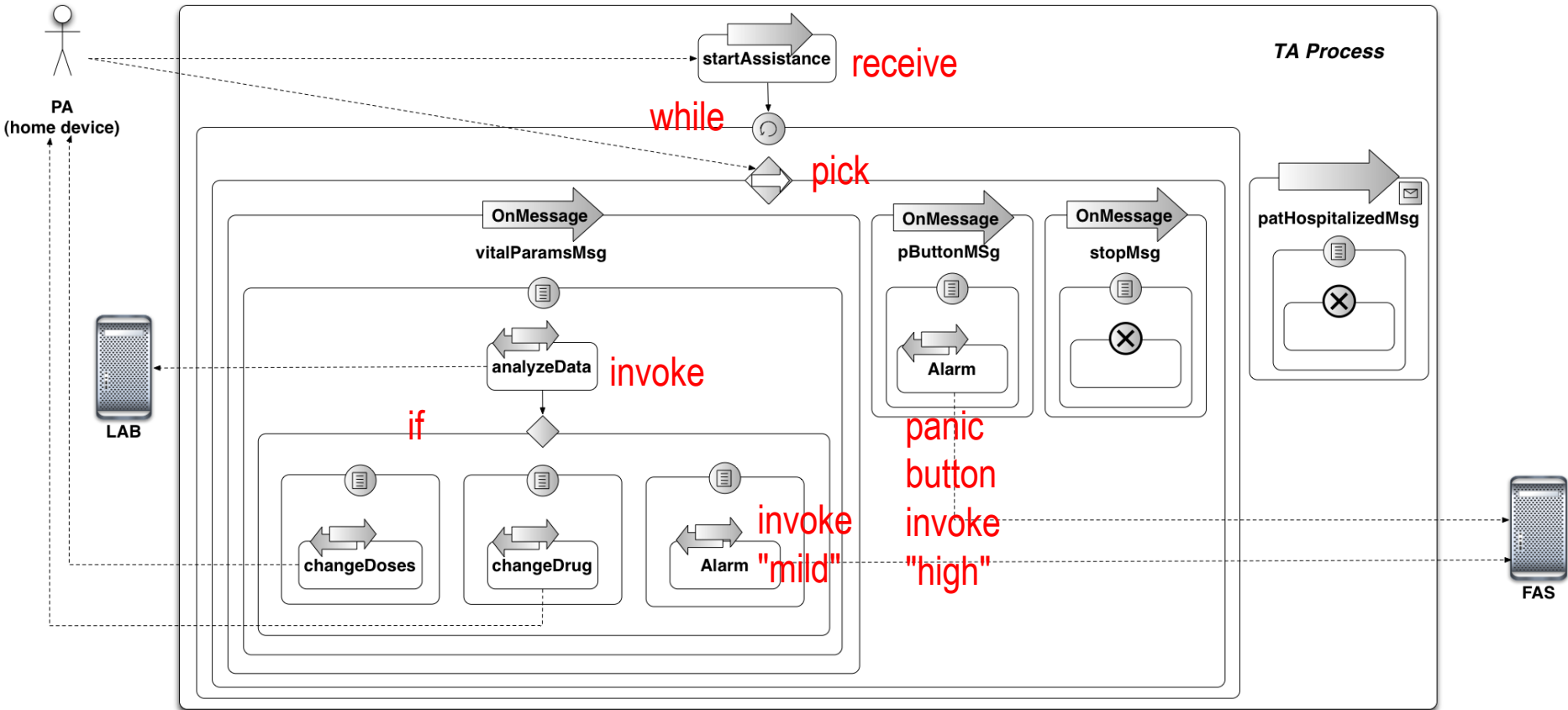


Variables

- Necessary to maintain the process state
- Their types can be:
 - WSDL message
 - XML type
 - XML Schema element
- Contents of (inbound and outbound) messages are stored in variables



The TeleAssistance (TA) Process





Assumed properties

■ LabServiceTime—Lab

after sending the patient's data to the lab, a reply is received within 1 hour

■ FASConfirmHospitalization—FA Squad

if the FAS is invoked three times over a week, with a "High" severity level for a certain patient, within one day a notification is received that the patient has been hospitalized



Promised properties

■ FASInvokeMildAlarm

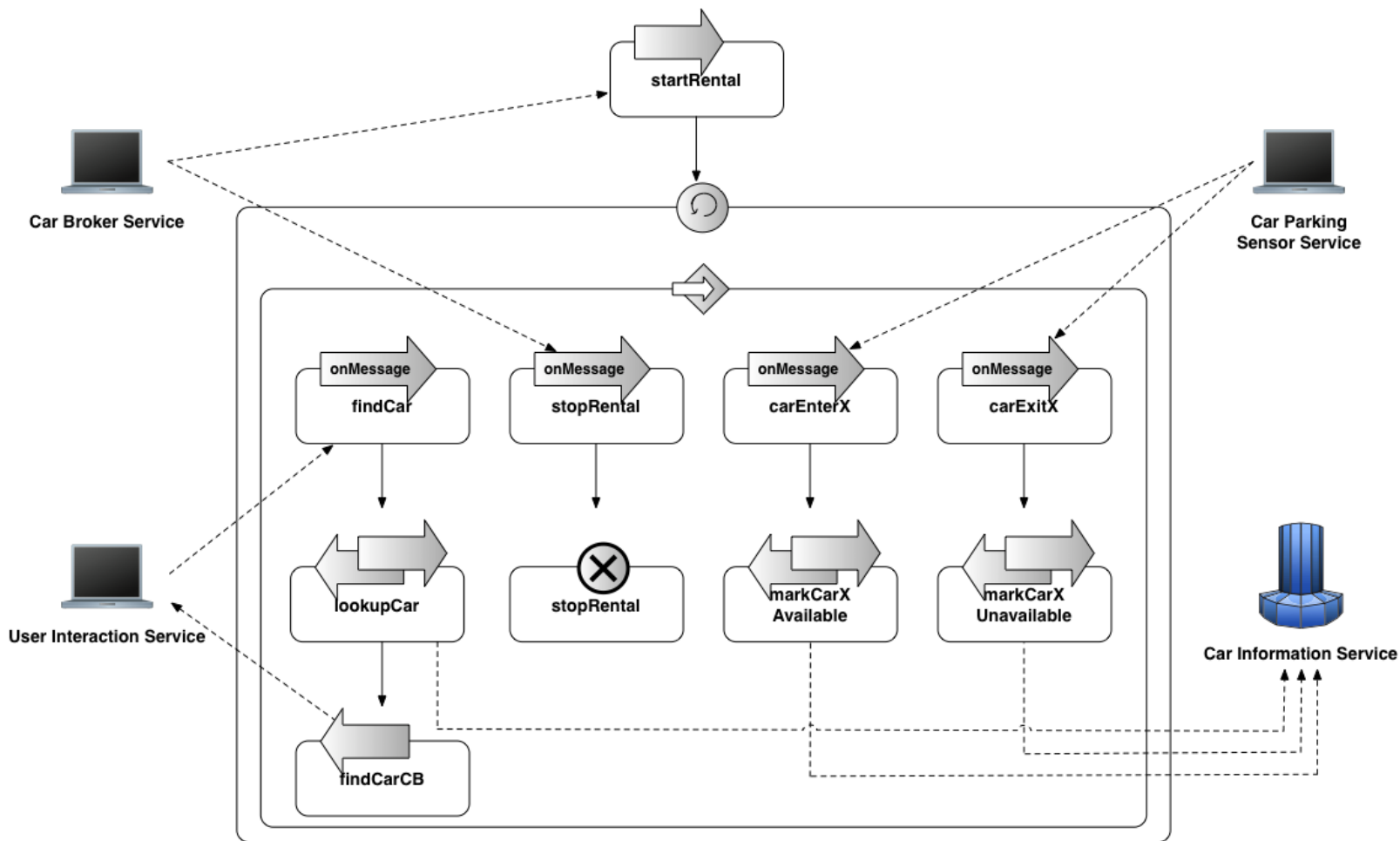
after receiving a message from the LAB indicating that an alarm must be issued to the FAS, the TA process must send a "Mild" alarm notification to the FAS service within four hours

■ MDCheckUp

if a certain patient pushes the pButtonMsg three times during a time span of a week, the patient must be hospitalized within one day



Car rental process





Sample properties

- **ParkingInOut (AP)**—car parking sensor service
between two events signaling that a car exits the parking, an event signaling entrance for the same car must occur
- **RentCar (PP)**
if a car enters the parking and does not exit until a client requests it for renting, then the request must succeed

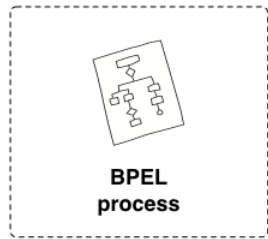
Two kinds of verification, one language



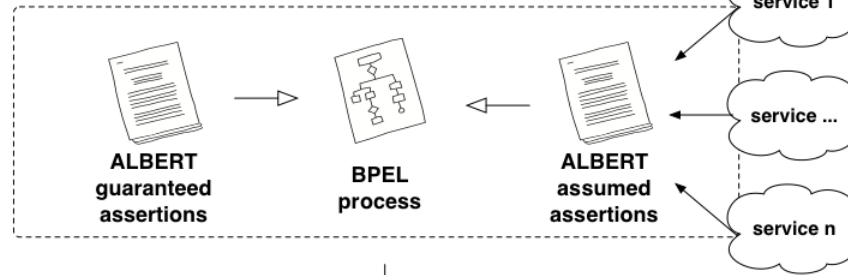
- ALBERT (Assertion Language for BPEL pRocess inTeractions)
 - can express assumptions and promises
- Can be used for two kinds of verification
 - **design-time** (model checking)
 - promised properties are satisfied by the workflow under the assumption that assumed properties hold
 - **run-time** (monitoring+ run-time verification)
 - checks if assumptions are valid
 - services satisfy their promises



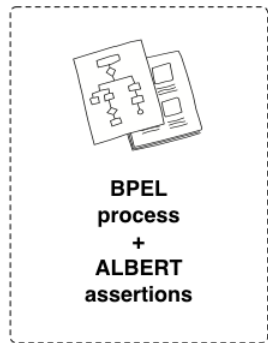
1 BPEL process design



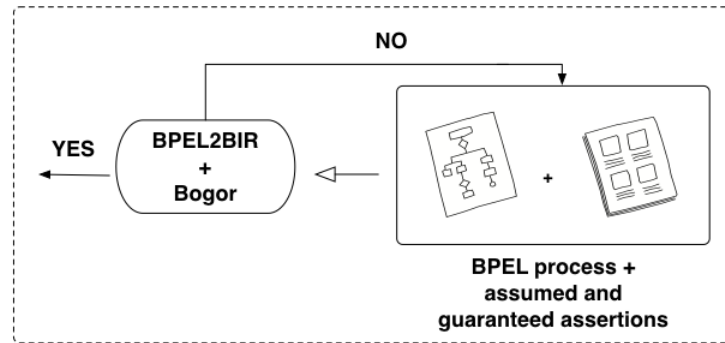
2 Annotation of the BPEL process with ALBERT assertions



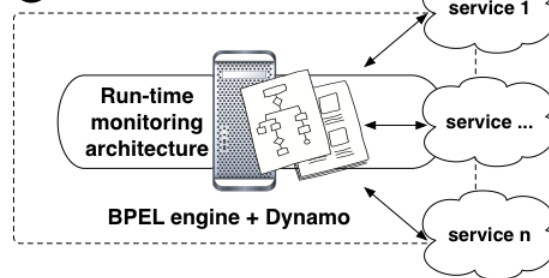
4 Deployment



3 Design-time verification



5 Run-time verification





ALBERT

- A linear temporal logic language
- **Variables** correspond to BPEL variables
- **State** a triple (V, I, t) , where
 - V is a set of $\langle \text{var}, \text{val} \rangle$ pairs
 - I is a location in the workflow: set of labels
 - t is the time at which the state is generated
- State changes are associated with location counter change in the workflow
 - internal activities (assign)
 - interactions with the world



ALBERT in a nutshell

- It predicates on variables
- Classical boolean operators and quantifications
- Event predicate
 - $\text{OnEvent}(XXX)$ true in a state if event XXX occurs in that state; e.g., $\text{onEvent}(\text{invoke_}XXX)$
 - true in a state if the service XXX is invoked in that state
- Future Temporal Operators
 - Becomes, Until, Within
- Functions
 - elapsed, past, count, ...



ALBERT—syntax

$\phi ::= \neg\phi \mid \phi \wedge \phi \mid \forall \text{var} \phi \mid \text{Becomes}(\phi) \mid \text{Until}(\phi, \phi) \mid \text{Within}(\phi, K) \mid \psi \text{ relop } \psi \mid \text{onEvent}(\mu)$

$\psi ::= \text{var} \mid \psi \text{ arop } \psi \mid \text{const} \mid \text{past}(\psi, \text{onEvent}(\mu)) \mid \text{count}(\phi, K) \mid \text{fun}(\psi, K) \mid \text{fun}(\psi, \text{onEvent}(\mu), K) \mid \text{elapsed}(\text{onEvent}(\mu))$

$\text{relop} ::= < \mid \leq \mid = \mid \geq \mid >$

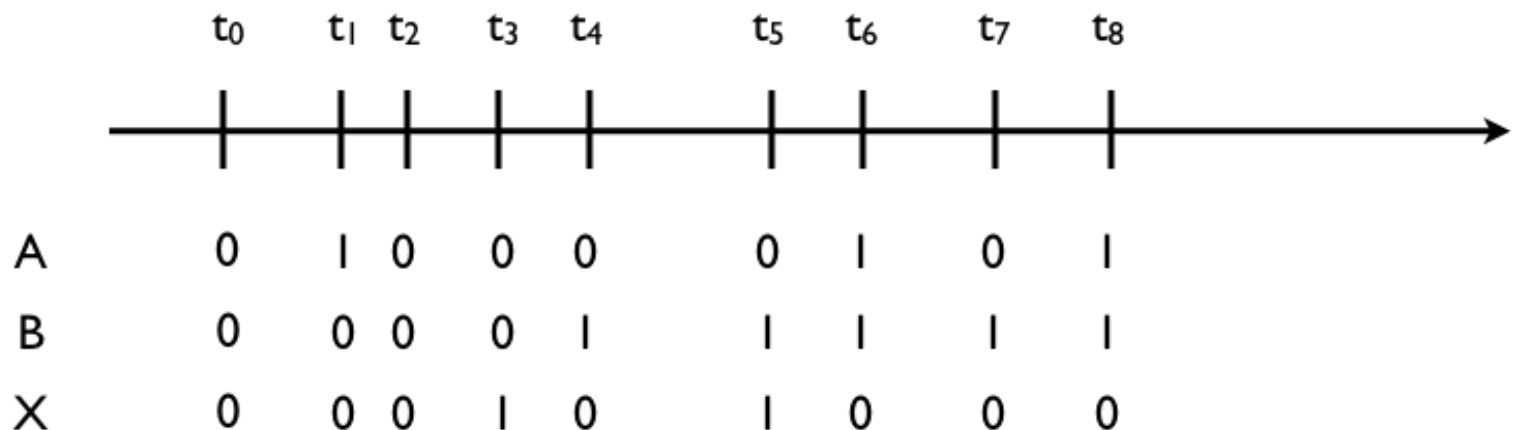
$\text{arop} ::= + \mid - \mid \times \mid \div$

$\text{fun} ::= \text{sum} \mid \text{avg} \mid \text{min} \mid \text{max} \mid \dots$



ALBERT—semantics

- Semantics is explained by referring to sequences of time-stamped states of the BPEL process (timed state word)
 - an infinite sequence s_0, s_1, s_2, \dots , where each s_i is a state (V_i, I_i, t_i)
 - the sequence is strictly monotonic (time consuming operation occurs in a transition)

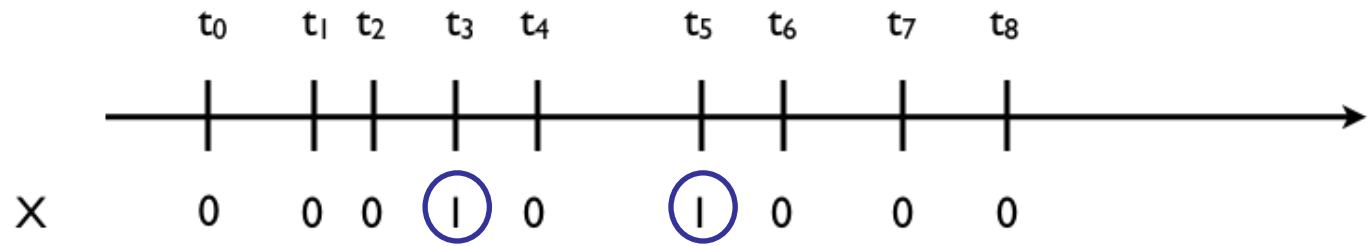




Becomes and Until

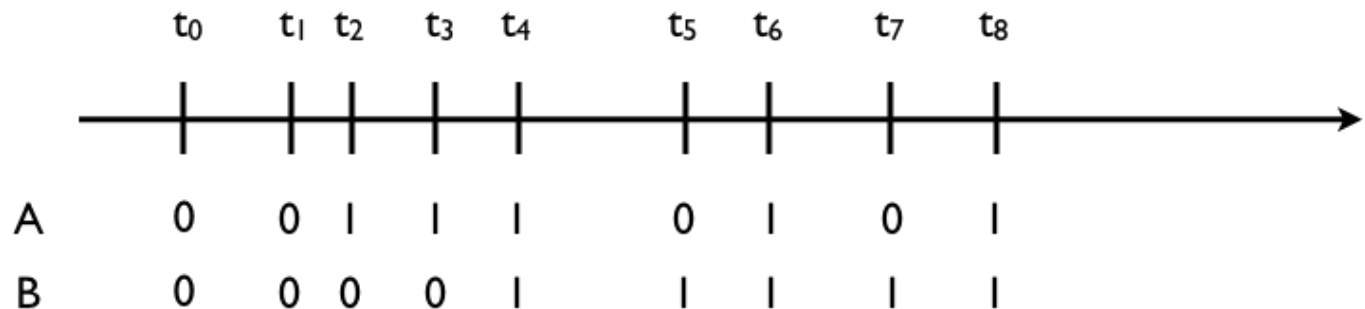
Becomes(X)

true when
evaluated
in t_3 and t_5



Until(A,B)

true when
evaluated
in t_2 (and
also in t_1)





Within

Within (X, K)

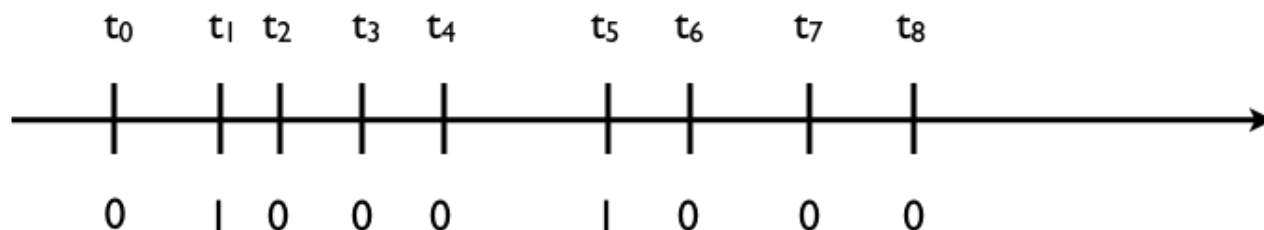
X true within K instants

true when

evaluated in t_2

with $t_5 - t_2 \leq K$

X





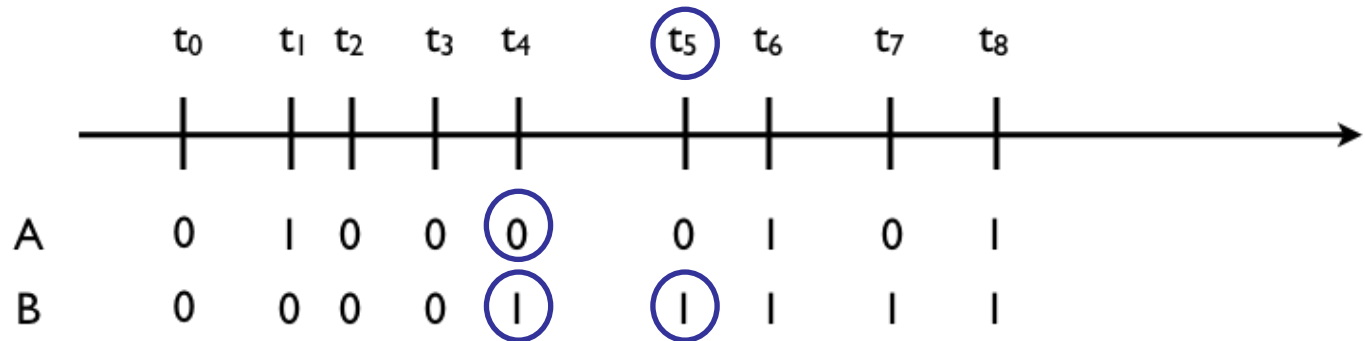
past and elapsed

$past(A, onEvent(B))$

= 0 when

evaluated in t_5 and in t_6

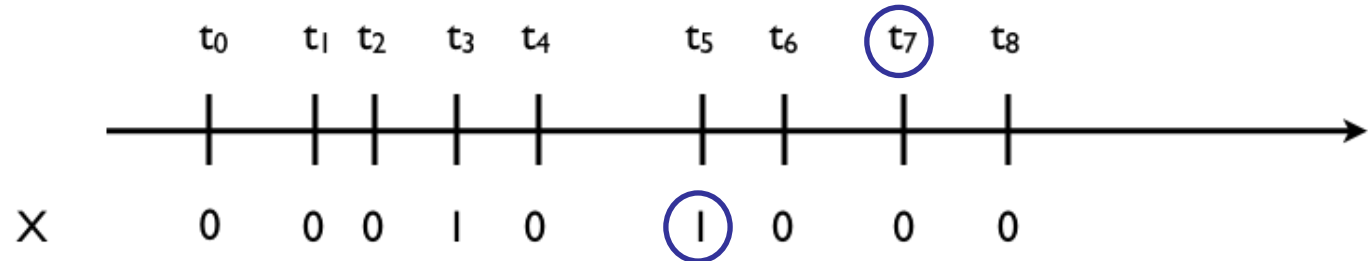
= 1 when evaluated in t_7



$elapsed(onEvent(X))$

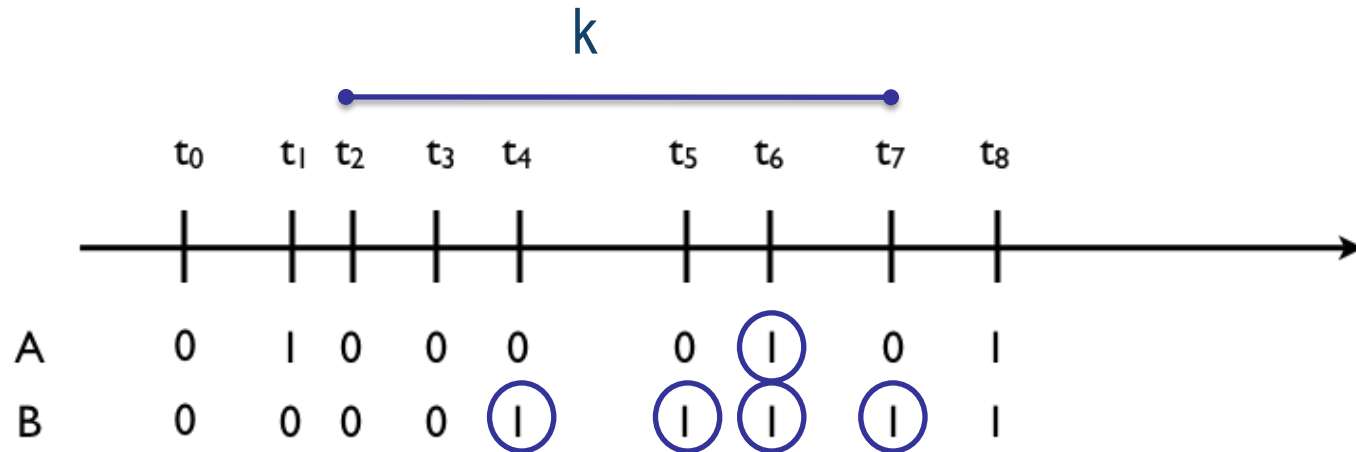
= $t_7 - t_5$ when

evaluated in t_7





count



- In t_7 (with $t_7 - t_2 \leq k$ and $t_7 - t_1 > k$):
 - $count(A, k) = 1$
 - $Becomes(count(B, k) = 4)$ is true



ALBERT properties

- Properties are in the form
it is always true that XXX holds
that is, they are process invariants
- In Albert, they have the form
Always XXX
 - which stands for ***XXX and not (true Until not XXX)***
- For convention, the outer Always is omitted



Useful derived operators

- We saw **Always** (also \square)
- **Eventually** (also \diamond)
 - $\diamond X$ defined as *true Until X*
- *When(X, Y)* when A is true in the future, B is also true
 - *When(X, Y)* defined as $\diamond X \rightarrow (\square X \text{ Until } X \wedge Y)$

Using ALBERT (TeleAssistance)



■ LabServiceTime (AP)

after sending the patient's data to the lab, a reply is received within 1 hour

```
onEvent(invoke_AnalyzeData) →  
Within(onEvent(receive_AnalyzeData), 60)
```



Using ALBERT (TA cont.)

■ AverageLabServiceTime (AP)

the average response time of requests to analyze data completed in past 10 hrs should be less than 45 min.

```
avg(elapsed(onEvent(invoke_AnalyzeData)),  
      onEvent(receive_AnalyzeData), 600) <= 45
```




Using ALBERT (TA cont.)

■ FASInvokeMildAlarm (PP)

after receiving a message from the LAB indicating that an alarm must be issued to the FAS, the TA process must send a "Mild" alarm notification to the FAS service within four hours

onEvent(receive_AnalyzeData) \wedge

$\$analysisResult/suggestion = 'sendAlarm'$

→

Within(*onEvent*(alarmNotif) \wedge $\$alarmNotif/level = 'mild'$), 240)



Using ALBERT (TA cont.)

■ MDCheckUp (PP)

if a certain patient sends the pButtonMsg three times during a time span of a week, the patient must be hospitalized within one day

$$\forall x (\text{Becomes}(\text{count}(\text{onEventI}(\text{pButtonMsg}) \wedge \$\text{alarmNotif}/\text{pId}=x, 10080) = 3)$$

→

$$\text{Within}(\text{onEvent}(\text{patHospitalized}) \wedge \$\text{patHospitalized}/\text{pID}=x, 1440))$$



Using ALBERT (CarRental)

■ ParkingInOut (AP)

between two events signaling that a car exits the parking, an event signaling entrance for the same car must occur

$$\forall x ((onEvent(carExit) \wedge \$carExit/carID=x) \rightarrow \\ Until(not (onEvent(carExit) \wedge \$carExit/carID=x), \\ onEventI(carEnter) \wedge \$carEnter/carID=x))$$



Using ALBERT (CR cont.)

■ CISUpdate (AP)

if a car is marked available in the Car InfoSyst and it is not marked unavailable until a lookUpCar is performed, then lookup for that car must show that the car is available

$$\forall x (onEvent(receive_MarkAvail) \wedge \$carInfo/carID=x \wedge$$

$$Until(not (onEvent(receive_MarkUnavail) \wedge \$carInfo/carID=x),$$

$$onEvent(invoke_LookUp) \wedge \$carInfo/carID=x)$$

→

$$When(onEvent(invoke_LookUp) \wedge \$carInfo/carID=x,$$

$$Eventually((onEvent(receive_LookUp) \wedge$$

$$\$carInfo/carID=x \wedge \$qRes/res!="no"))))$$



Using ALBERT (CR cont.)

■ RentCar (PP)

if a car enters the parking and does not exit until a client requests it for renting, then the request must succeed

$$\forall x (onEvent(carEnter) \wedge \$carEnter/carID=x \wedge$$

$$Until(not (onEvent(carExit) \wedge \$carEnter/carID=x),$$

$$onEvent(invoke_FindCar) \wedge \$carInfo/carId=x))$$

→

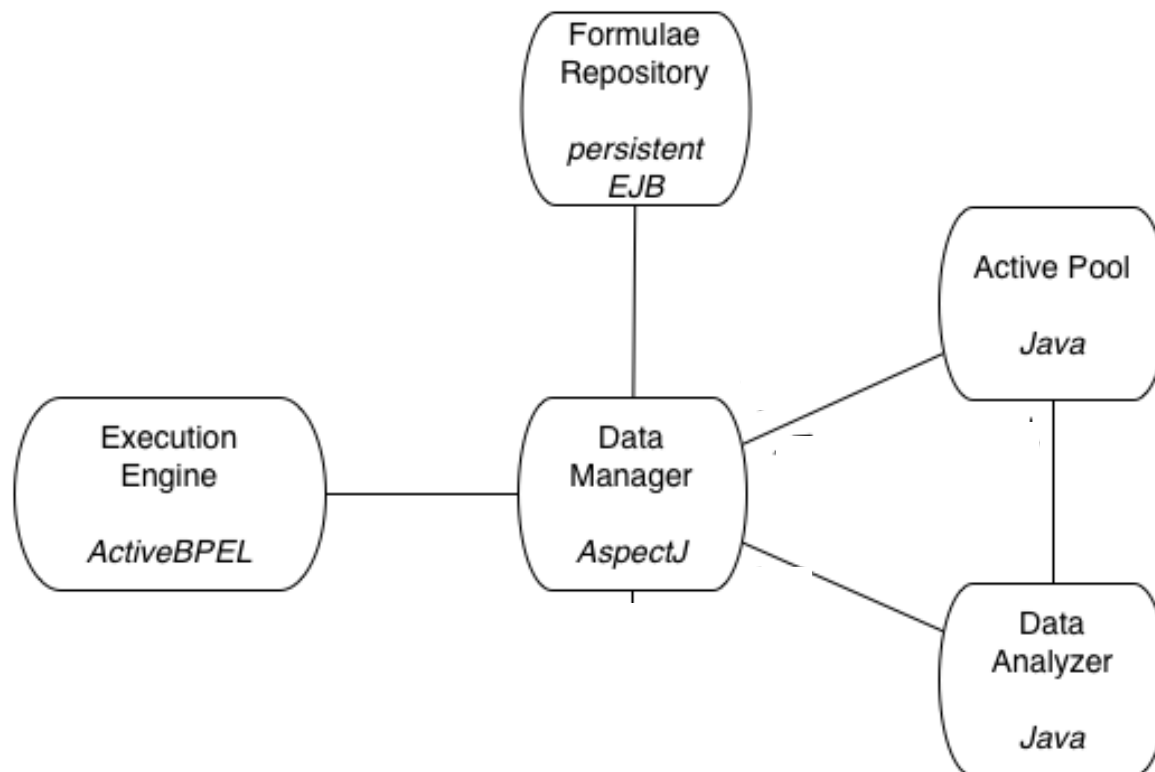
$$When(onEvent(invoke_FindCar) \wedge \$carInfo/id=x,$$

$$Eventually((onEvent(invoke_FindCarCB) \wedge \$carInfo/carId=x$$

$$\wedge \$queryResult/res!="no"))))$$



Execution and monitoring





Properties of run-time verification

- Size of the state history kept in the ActivePool
 - Maximum among:
 - maximum nesting level of *past* functions
 - 1 (if there is at least a *Becomes* predicate)
 - maximum number of states needed for the various *count* and *fun* time windows
- Number of threads required for the verification
 - 1, for each *Until* (sub)formula
 - number of states in the sequence of process states that may occur in a time interval long K , for each *Within(A,K)* (sub)formula